

# The Latest and Greatest on Surface Emissions Monitoring for Methane at Landfills

Tarek Abichou, Ph.D. P.E.



FAMU-FSU  
College of Engineering

Hinkley Center  
for Solid and Hazardous  
Waste Management



# Motivations

- Ambient air CH<sub>4</sub> concentration measurements are already frequently obtained and monitored in many municipal solid waste landfills.
- Can we beneficially use the quarterly **SEMs** or **Enhanced SEMs** to provide an estimate of **Landfill Total Emissions** ?

## **Applications:** What else can we use them for?

- Determine **Total Landfill Emissions Estimates**
- Identify high emissions **point sources**
- Identify high emissions **areas sources**
- Test different **remedial actions**
  - Estimate emissions reduction after remediation (Fixing the exceedances, placing more cover, adding more wells, increasing vacuum, etc...)

## Making more use of SEMs

Surface Methane Emission (SEM) monitoring is already used as part of New Source Performance Standards (NSPS), Title 40 Code of Federal Regulations Section 60.755(c) and (d).  
**Four (4) times per year**

# ppm

## SEM2Flux Tool

Assume measurement locations as **receptors**, affected by emissions from adjacent area on the landfill: **sources** of emissions.

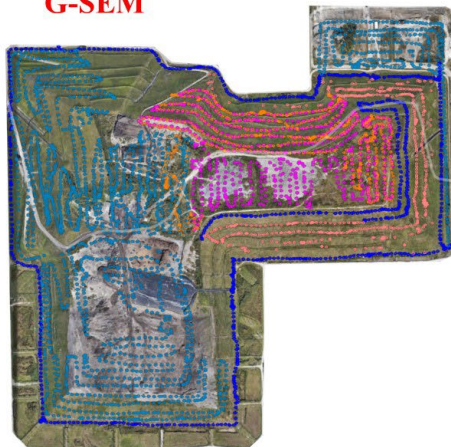
These **sources** are considered point sources and are responsible for the concentrations measured at the **receptors**.



(Hicks 2017)

### Landfill with Ground, Drone, and TCM Measurements

#### G-SEM



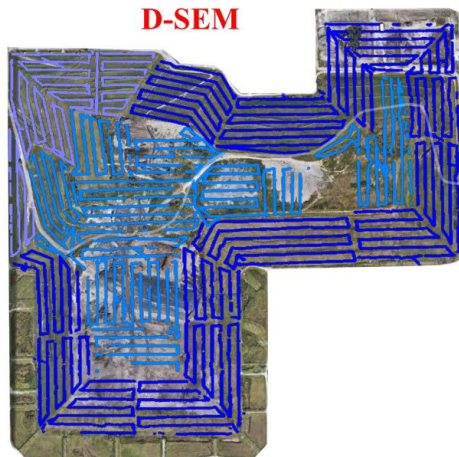
4,894 readings

Equivalent 27 readings per hectare.

Measured concentrations 21 exceeding 500 ppm.

Not Statistically Different

#### D-SEM



51,867 readings

Equivalent 285 readings per hectare.

Measured concentrations 7 exceeding 500 ppm.

# Kg/hr

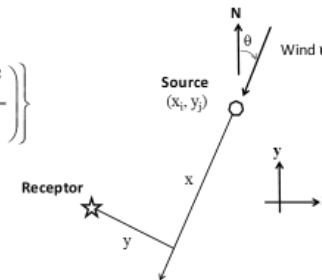
## SEM2Flux Tool

### Gaussian Dispersion Equation

$$C(x, y, z, H) = \frac{Q}{2\pi\mu\sigma_y\sigma_z} \exp\left(-\frac{1}{2} \frac{y^2}{\sigma_y^2}\right) \left\{ \exp\left(-\frac{1}{2} \frac{(z-H)^2}{\sigma_z^2}\right) + \exp\left(-\frac{1}{2} \frac{(z+H)^2}{\sigma_z^2}\right) \right\}$$

For ground-level sources and receptors ( $z = 0$  and  $H = 0$ )

$$C = \frac{Q}{\pi\mu\sigma_y\sigma_z} \exp\left[-\frac{1}{2} \frac{y^2}{\sigma_y^2}\right]$$



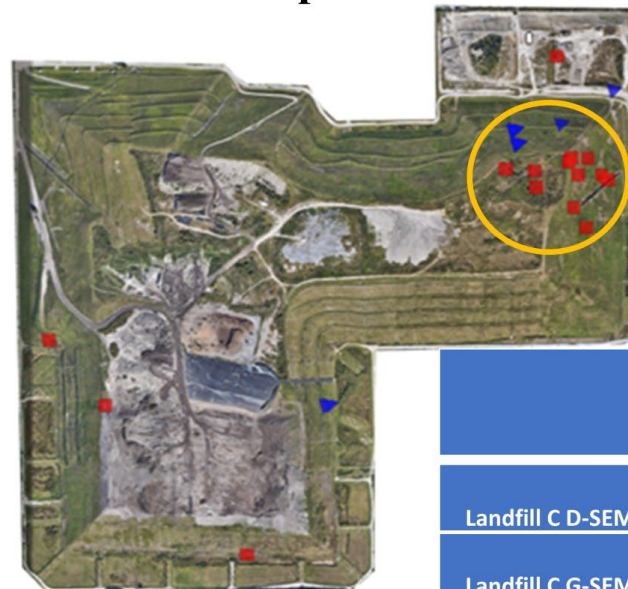
The predicted methane concentration in a receptor point  $i$  ( $C_{i, predicted}$ ) is calculated through summing up all contributions ( $C_{ij}$ ) of assumed source points  $j$  ( $j=1, \dots, n$ ).

$$C_{i, predicted} = \sum_{j=1}^n C_{i,j}$$

Calculating predicted concentration for all receptor points ( $i=1, \dots, m$ ) results in a vector of predicted concentration ( $C_{predicted}$ ).

Search for the **best-fit source configuration** is formulated as an optimization problem that consists of residual minimization under bound constraints.

## SEM2Flux Output - Results



SEM2Flux D-SEM Data Major Source Locations  
SEM2Flux G-SEM Data Major Source Locations

Confirmation of GCS Construction activities (trenching into waste. Etc..)

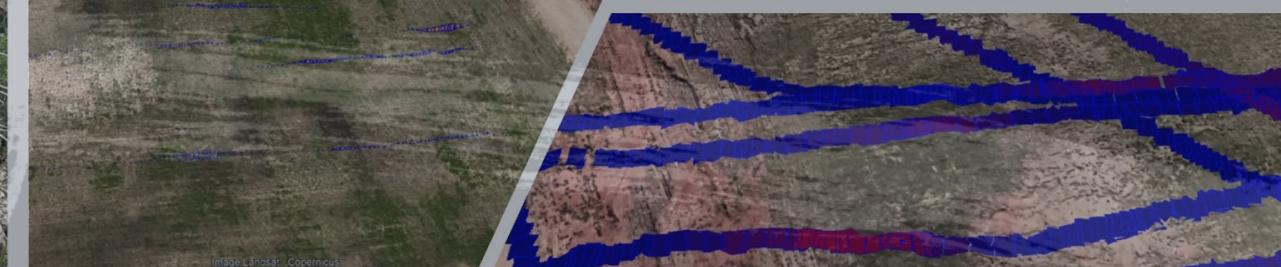
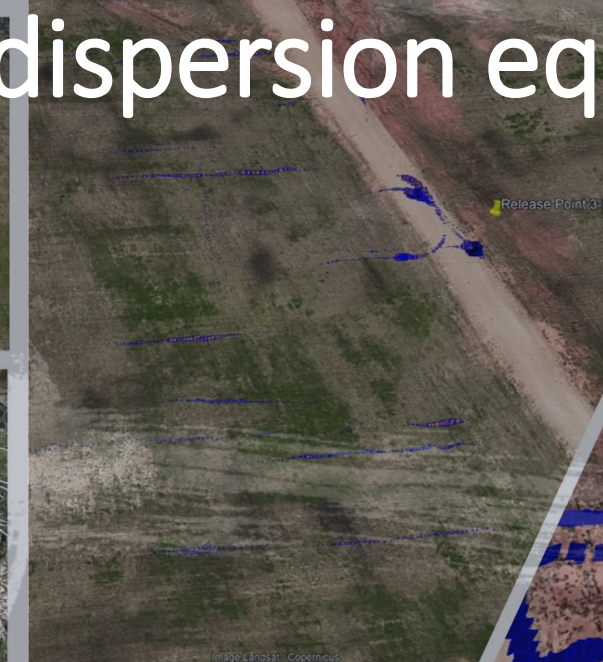
Carbon Mapper Flight Confirmed No Detection 4/14/2022 -4/16/2022

	Date	N. Major Sources	Total Fugitive Emissions (Kg/hr)	StDev (Kg/hr)
Landfill C D-SEM	4/14/2022	15	657	214
Landfill C G-SEM	4/14-4/16 2022	12	573	99



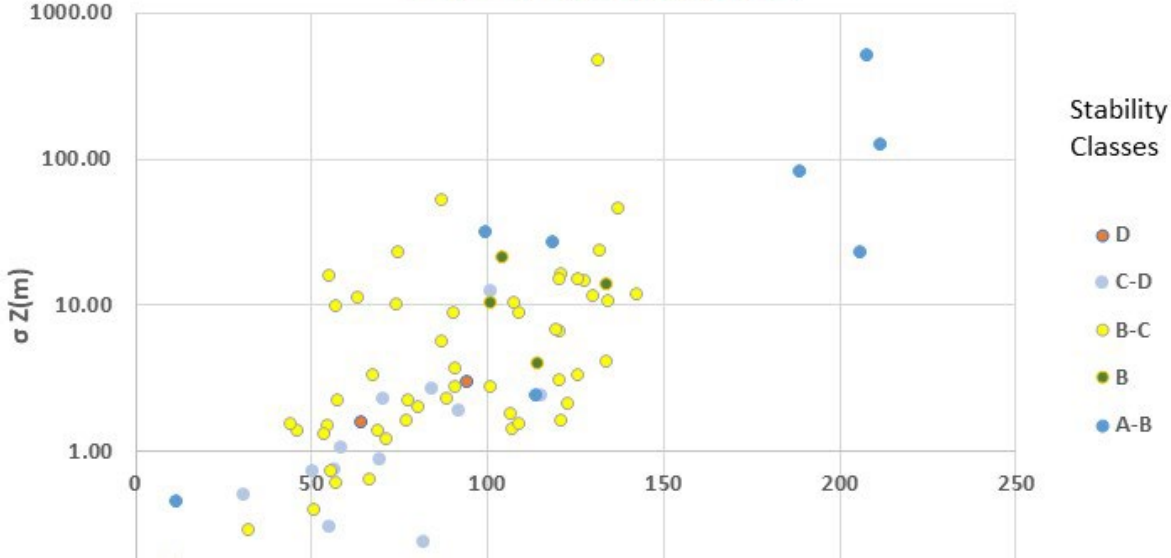
# Controlled Releases at Leon County Landfill

## Develop near-field dispersion equations

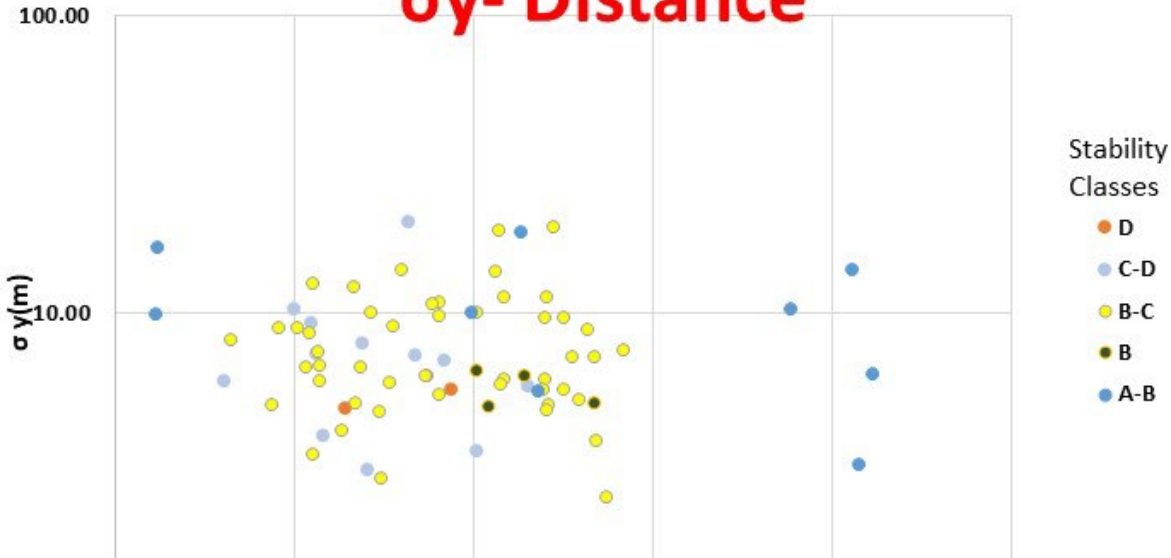


# Controlled Releases at Leon County Landfill: Calibration of Dispersion Coefficients

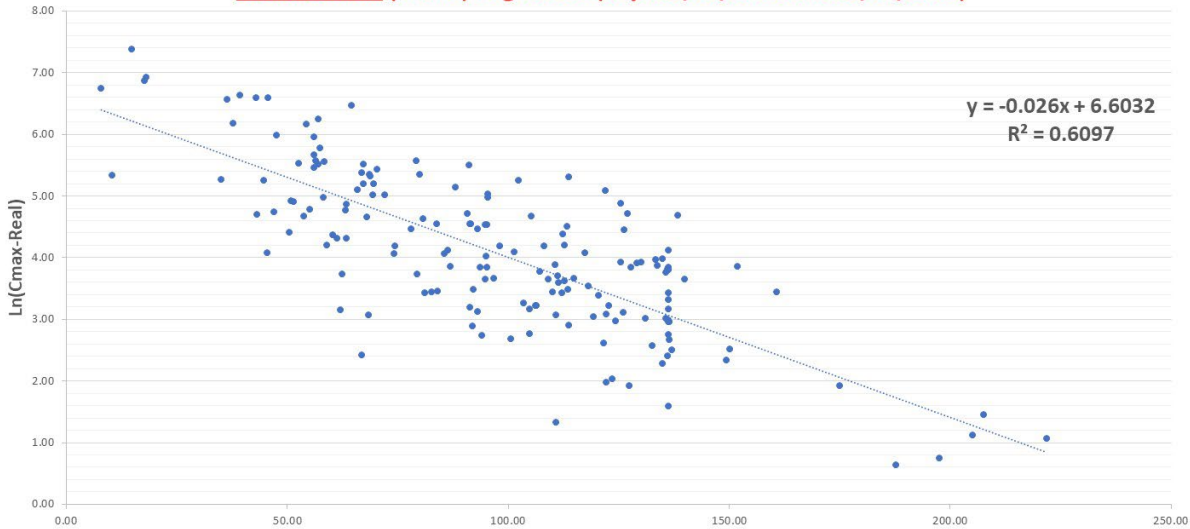
## $\sigma_Z$ -Distance



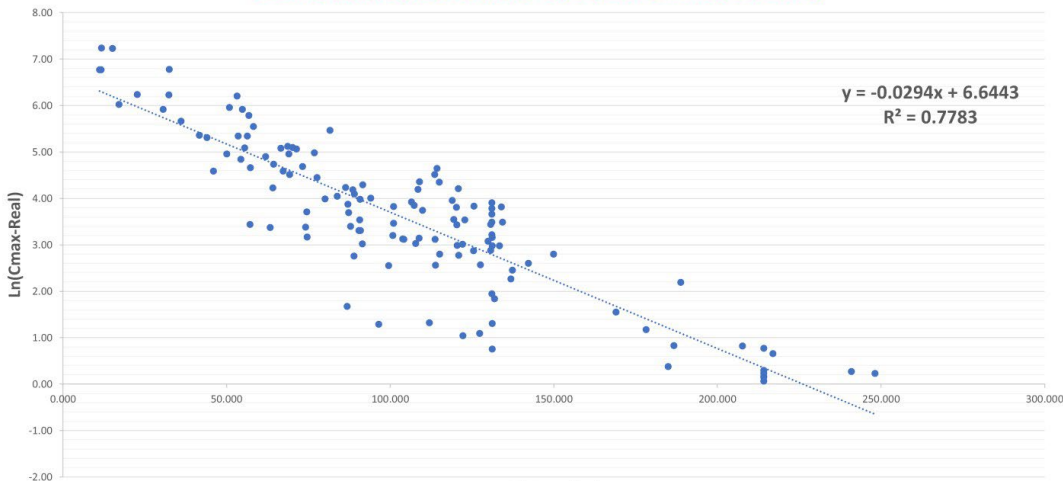
## $\sigma_y$ -Distance



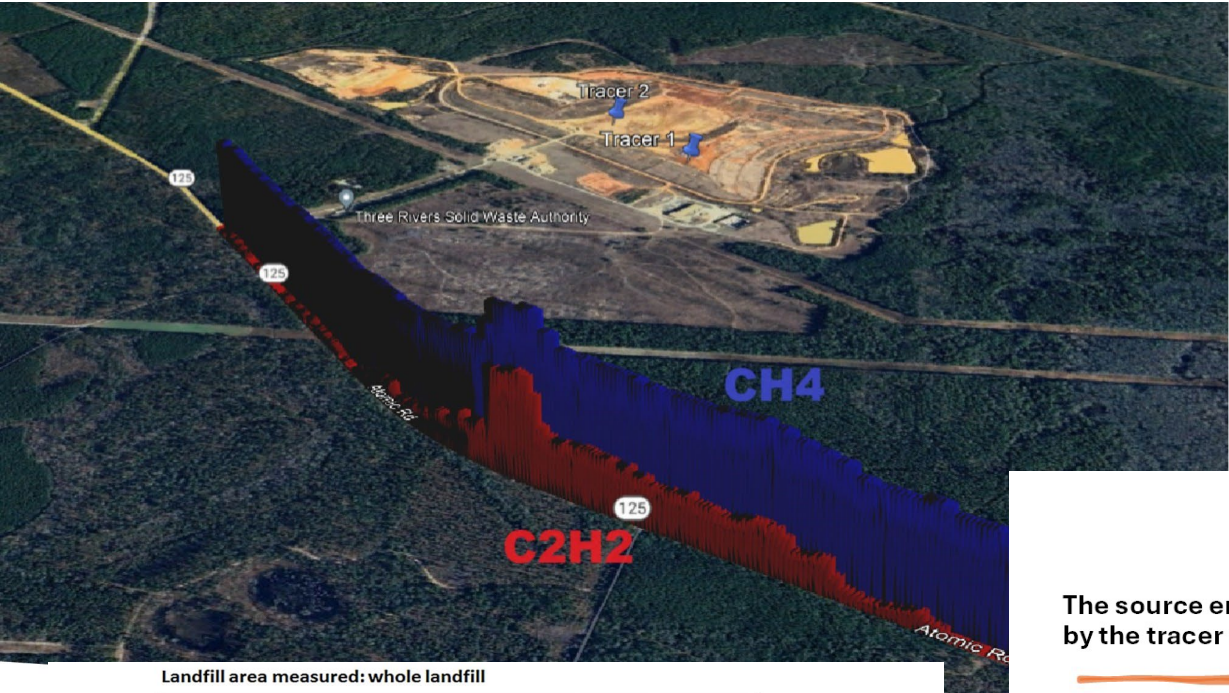
Elevated-data (Drone) Regression (days 03/30/2023 and 03/31/2023)



Ground-data Regression (days 03/30/2023 and 03/31/2023)

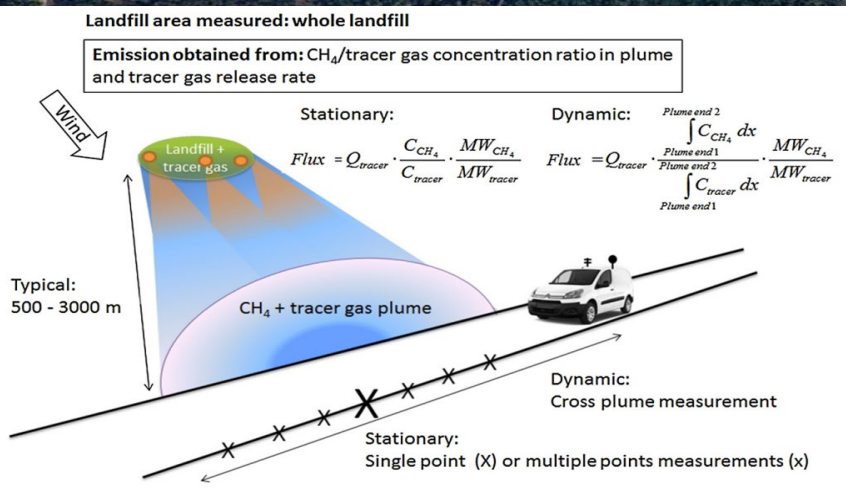


# Ground Truthing: Performed Tracer Correlation Method (TCM) tests to obtain “most likely estimate” of true total emissions from the landfill



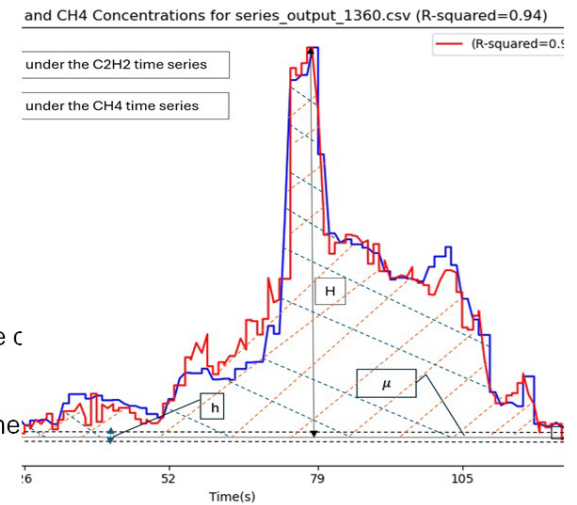
## Trained, Calibrated, and Verified Approach

The source emission rate is calculated for each transect using the ratio ( $v$ ) of CH<sub>4</sub> and C<sub>2</sub>H<sub>2</sub> areas, multiplied by the tracer release rate ( $Q_t$ ) and the ratio of the molecular weights of CH<sub>4</sub> ( $M_{CH_4}$ ) and C<sub>2</sub>H<sub>2</sub> ( $M_{C_2H_2}$ ).



$$Q_{CH_4,v} = (v)Q_t \frac{M_{CH_4}}{M_{C_2H_2}}$$

- $Q_{CH_4,v}$  : the source emission rate
- $Q_t$  : the tracer release rate
- $M_{CH_4}$  : molecular weights of CH<sub>4</sub>
- $M_{C_2H_2}$  : molecular weights of C<sub>2</sub>H<sub>2</sub>
- $v = \frac{\int_{t_0}^{t_f} (y(t) - \mu_y) dt}{\int_{t_0}^{t_f} (x(t) - \mu_x) dt}$
- $y(t)$  : CH<sub>4</sub> respective time series ( $t_0$  is the start time,  $t_f$  is the end time)
- $\mu_y$  : background concentrations for CH<sub>4</sub>
- $x(t)$  : C<sub>2</sub>H<sub>2</sub> respective time series ( $t_0$  is the start time,  $t_f$  is the end time)
- $\mu_x$  : background concentrations for C<sub>2</sub>H<sub>2</sub>



(Green et al. 2009, Mønster et al. 20

# Project Output

## Two versions:

**Version 1:** uses SEM locations as receptors, affected by emissions from a set of adjacent sources on the landfill using wind direction. **(Focus on Large Point Sources)**

**Version 2:** uses SEMs and develop a geospatial approach to estimate area flux ( $\text{g}/\text{m}^2/\text{d}$ ) for all areas under waste. **(Focus on Area Emissions Flux)**

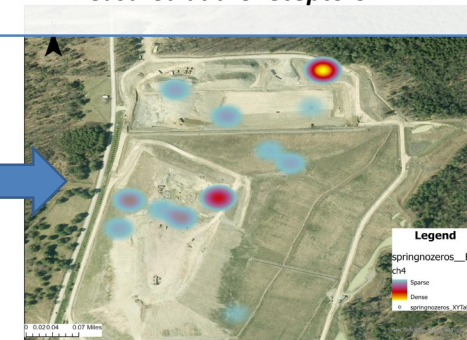
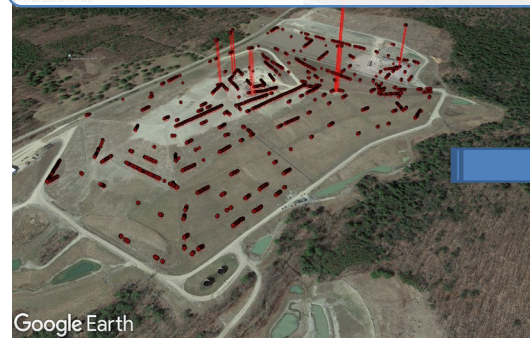
## Applications:

- Can we assign an emission reduction in mass/time to an improvement in LFG management practices
- Can we update the emissions **Flux** estimates once remediation are performed (Fixing the exceedances, placing more cover, adding more wells, increasing vacuum, etc...)

PPM  $\xrightarrow{\text{SEM2Flux}}$  Kg/hr

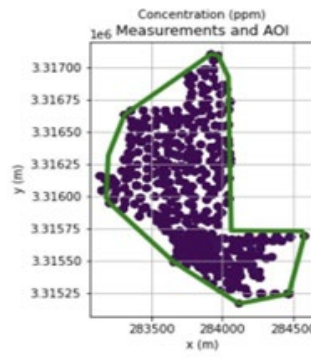
Assume measurement locations as *receptors*, affected by emissions from adjacent area on the landfill: *sources* of emissions.

These *sources* are considered point sources and are responsible for the concentrations measured at the *receptors*.

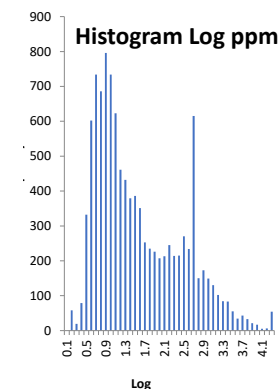


PPM  $\xrightarrow{\text{SEM2Flux}}$   $\text{g}/\text{m}^2/\text{d}$   
Kg/hr

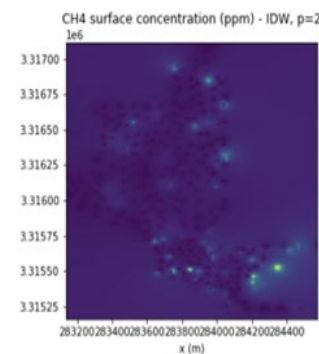
SEM Data  
Ground or Drone



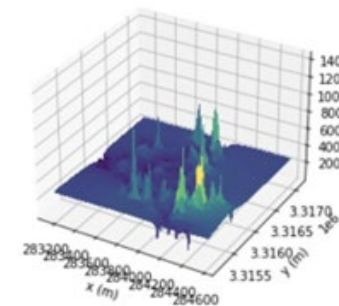
Log Transformation  
of SEM Data



Using Inverse Distance  
Weighing (IDW) to  
predict Local Log(ppmv)




Use Simple ppm to  
 $\text{g}/\text{m}^2/\text{d}$  Correlation to  
Predict Area Flux





Article

## Using Ground- and Drone-Based Surface Emission Monitoring (SEM) Data to Locate and Infer Landfill Methane Emissions

Tarek Abichou <sup>1,\*</sup>, Nizar Bel Hadj Ali <sup>2</sup> , Sakina Amankwah <sup>1</sup>, Roger Green <sup>3</sup> and Eric S. Howarth <sup>4</sup>

### SEM2Flux Tool – Point Source Locating

Assume measurement locations as **receptors**, affected by emissions from adjacent area on the landfill: **sources** of emissions.

These **sources** are considered point sources and are responsible for the concentrations measured at the **receptors**.

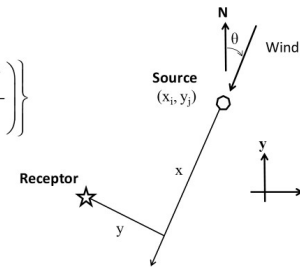
### SEM2Flux Tool

Gaussian Dispersion Equation

$$C(x, y, z, H) = \frac{Q}{2\pi u \sigma_y \sigma_z} \exp\left(-\frac{1}{2} \frac{y^2}{\sigma_y^2}\right) \left\{ \exp\left(-\frac{1}{2} \frac{(z-H)^2}{\sigma_z^2}\right) + \exp\left(-\frac{1}{2} \frac{(z+H)^2}{\sigma_z^2}\right) \right\}$$

For **ground-level sources and receptors** ( $z = 0$  and  $H = 0$ )

$$C = \frac{Q}{\pi u \sigma_y \sigma_z} \exp\left[-\frac{1}{2} \frac{y^2}{\sigma_y^2}\right]$$



The predicted methane concentration in a receptor point  $i$  ( $C_{i, predicted}$ ) is calculated through summing up all contributions ( $C_{ij}$ ) of assumed source points  $j$  ( $j=1, \dots, n$ ).

$$C_{i, predicted} = \sum_{j=1}^n C_{i, j}$$

Calculating predicted concentration for all receptor points ( $i=1, \dots, m$ ) results in a vector of predicted concentration ( $C_{predicted}$ ).

Search for the **best-fit source configuration** is formulated as an optimization problem that consists of residual minimization under bound constraints.



## Focus on Localization



# SEM2Flux Source Localization (Timeline)

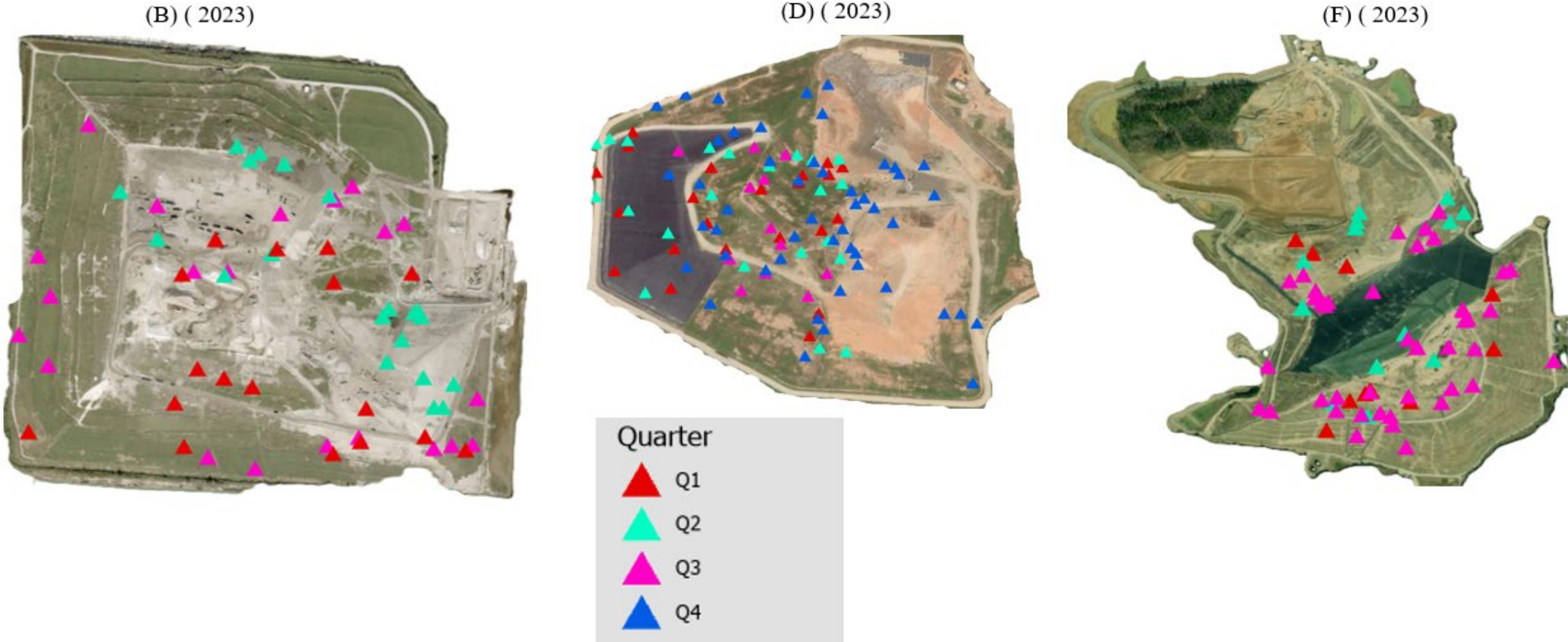
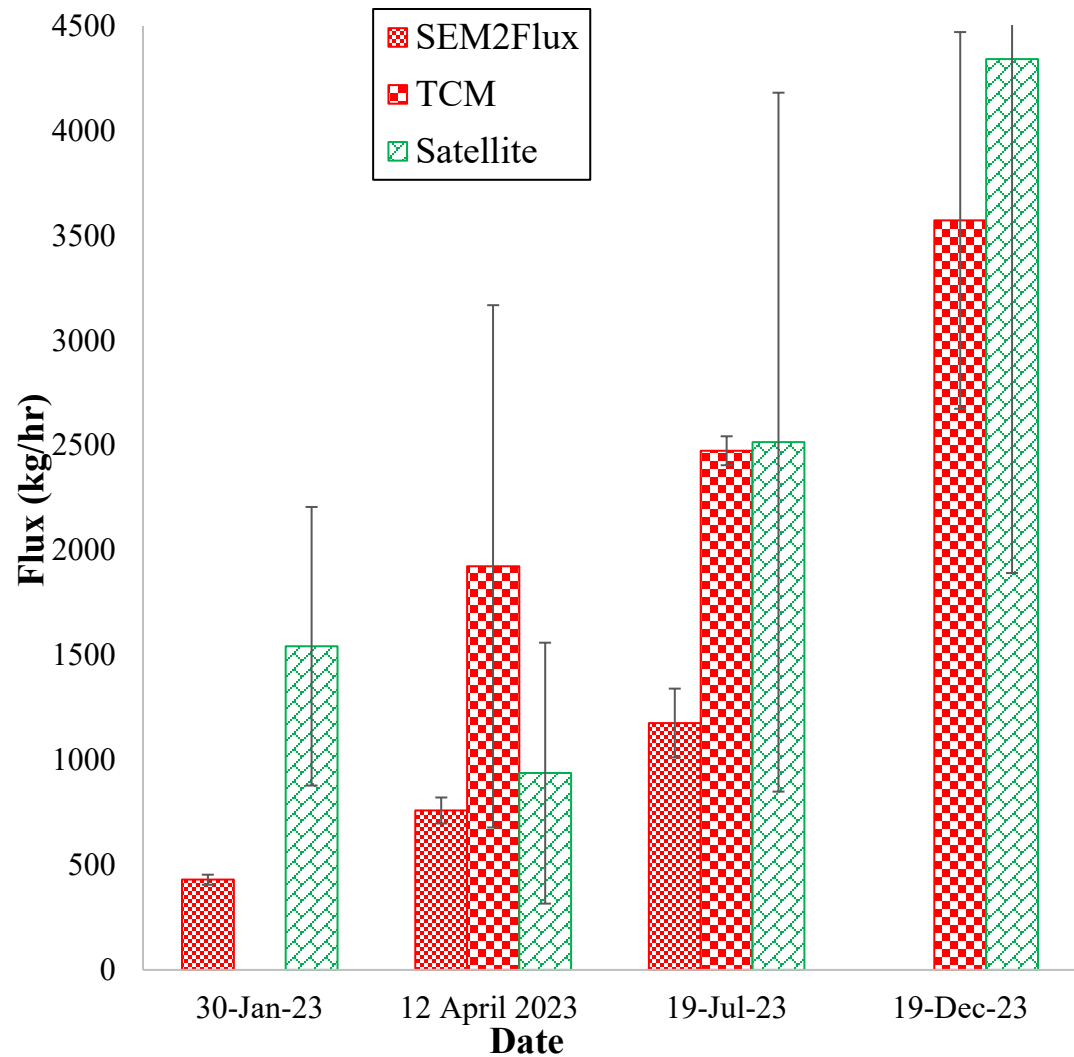


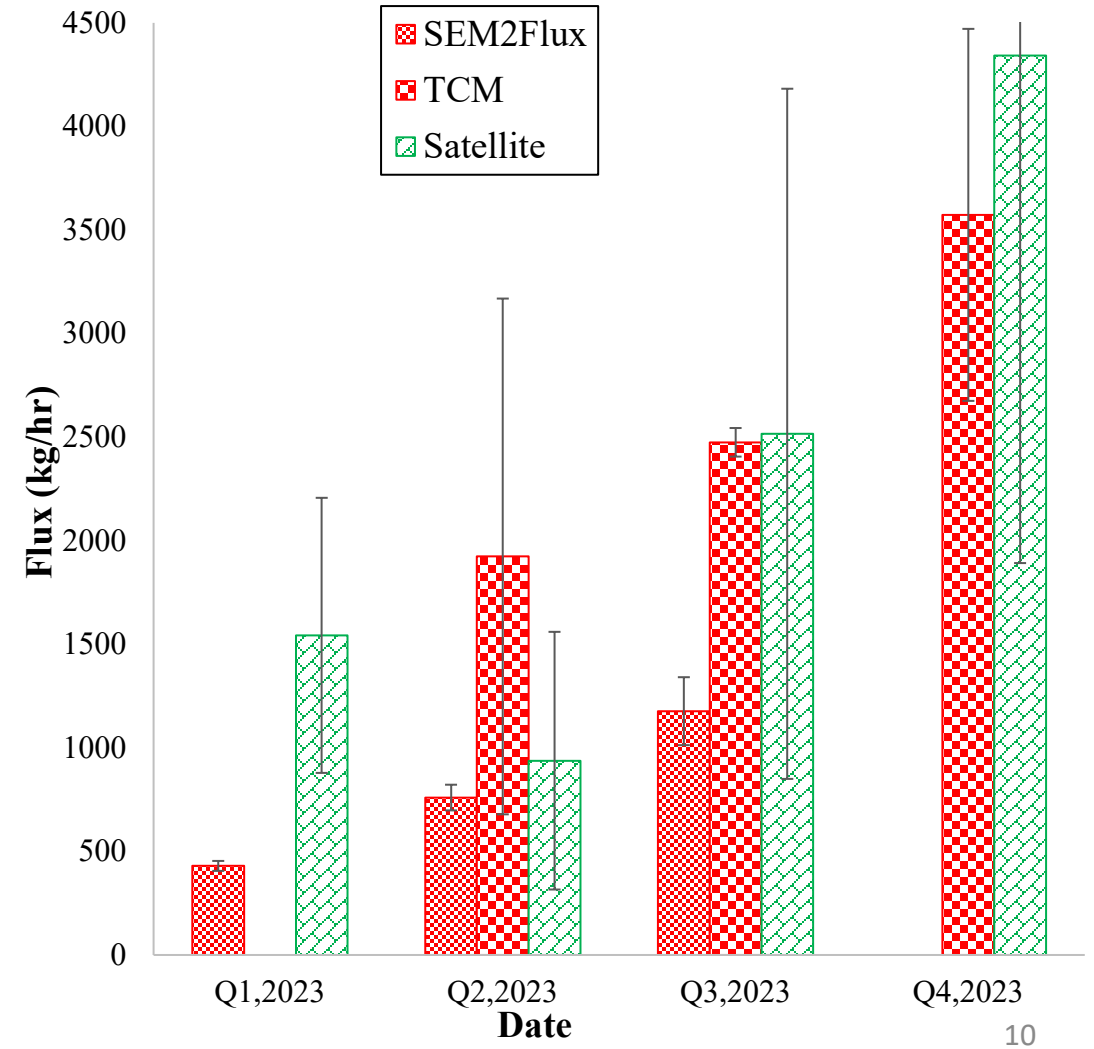
Figure A Methane emission source location from G-SEM SEM2Flux simulation.(B, D, F) are Landfills B, D and F respectively

# Total Landfill Emissions Estimation

## Landfill F



## Landfill F



# SEM2Flux Approach 2: Geospatial

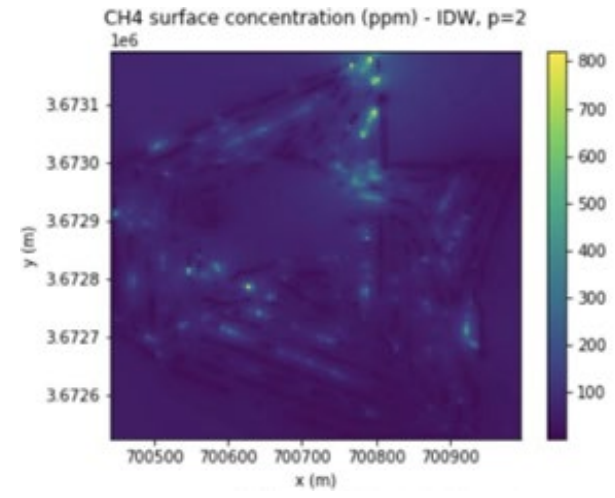
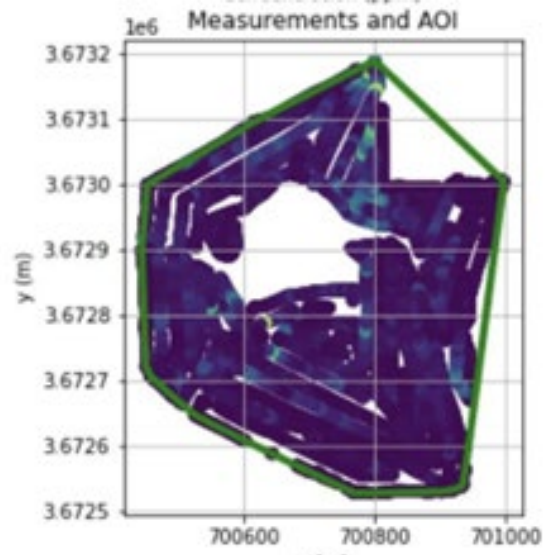
## Developed Geospatial Approach to Transform SEM Data to Local Emissions Flux



**SEM Data  
Ground or Drone**

**Log Transformation  
of SEM Data**

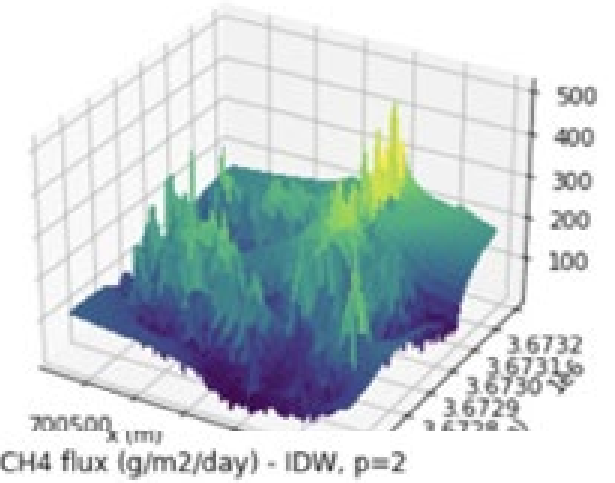
**Using Inverse Distance Weighing (IDW) to  
predict Local Log(ppmv)**



**Use Simple ppm to  
g/m<sup>2</sup>/d Correlation to  
Predict Area Flux**

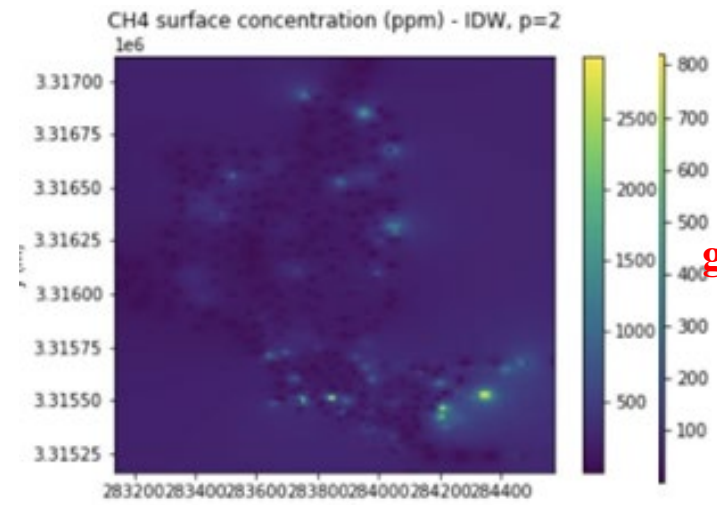
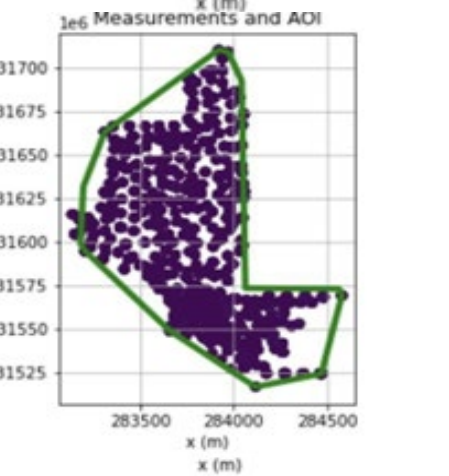
Estimation of total landfill surface methane emissions using geospatial approach combined with measured surface ambient air methane concentrations

CH4 flux (g/m<sup>2</sup>/day) - IDW, p=2

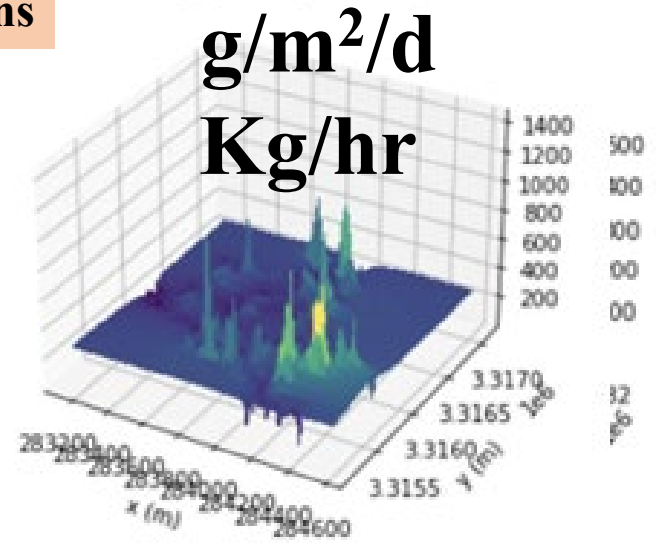


**Focus on area  
emissions flux, and  
total landfill emissions**

**g/m<sup>2</sup>/d  
Kg/hr**

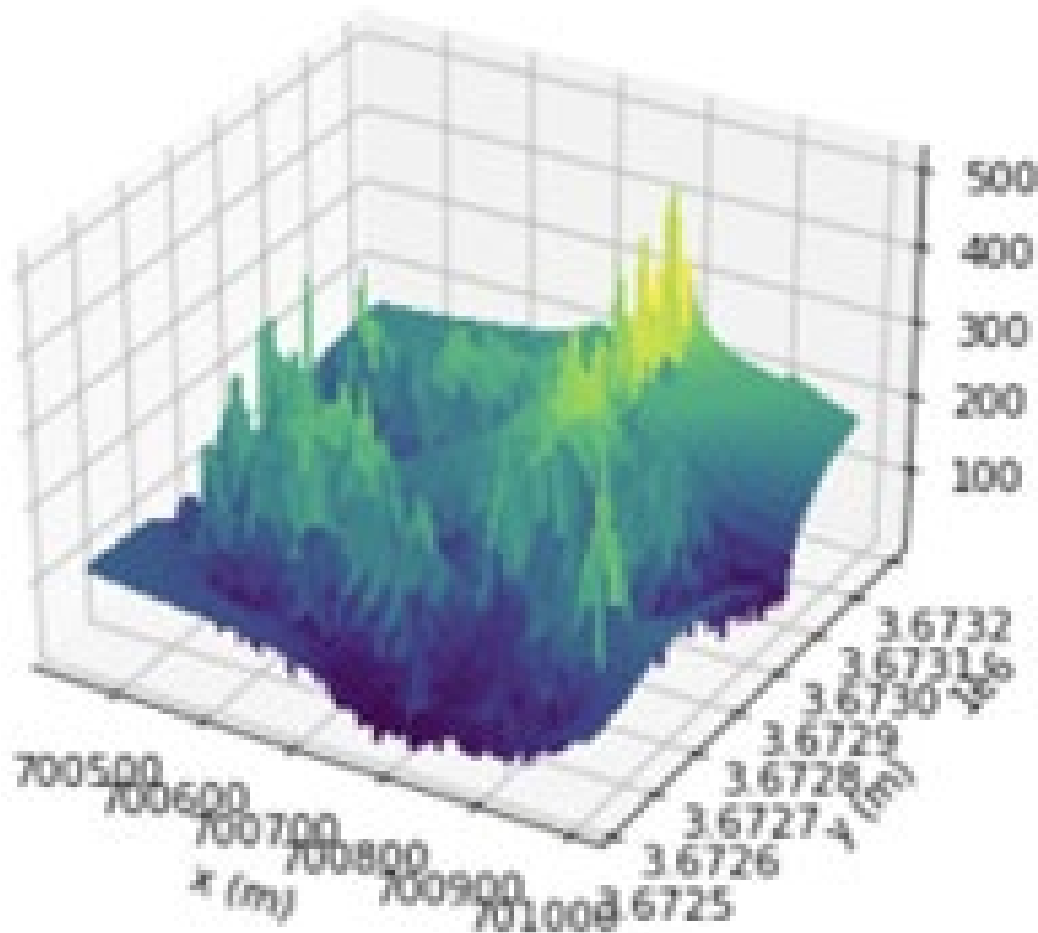


**Use Simple ppm to  
g/m<sup>2</sup>/d Correlation to  
Predict Area Flux**



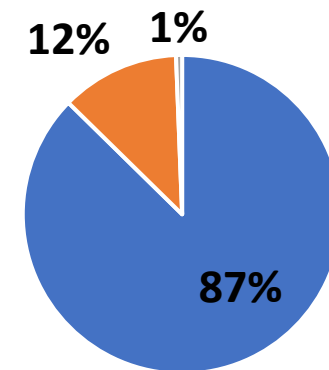
# SEM2Flux Approach 2: Geospatial Actionable Output of Approach

CH4 flux (g/m<sup>2</sup>/day) - IDW, p=2



Emission rate kg/hr	Low flux contribution kg/hr	Medium flux contribution kg/hr	High flux contribution kg/hr
406	354.8	48.9	2.5

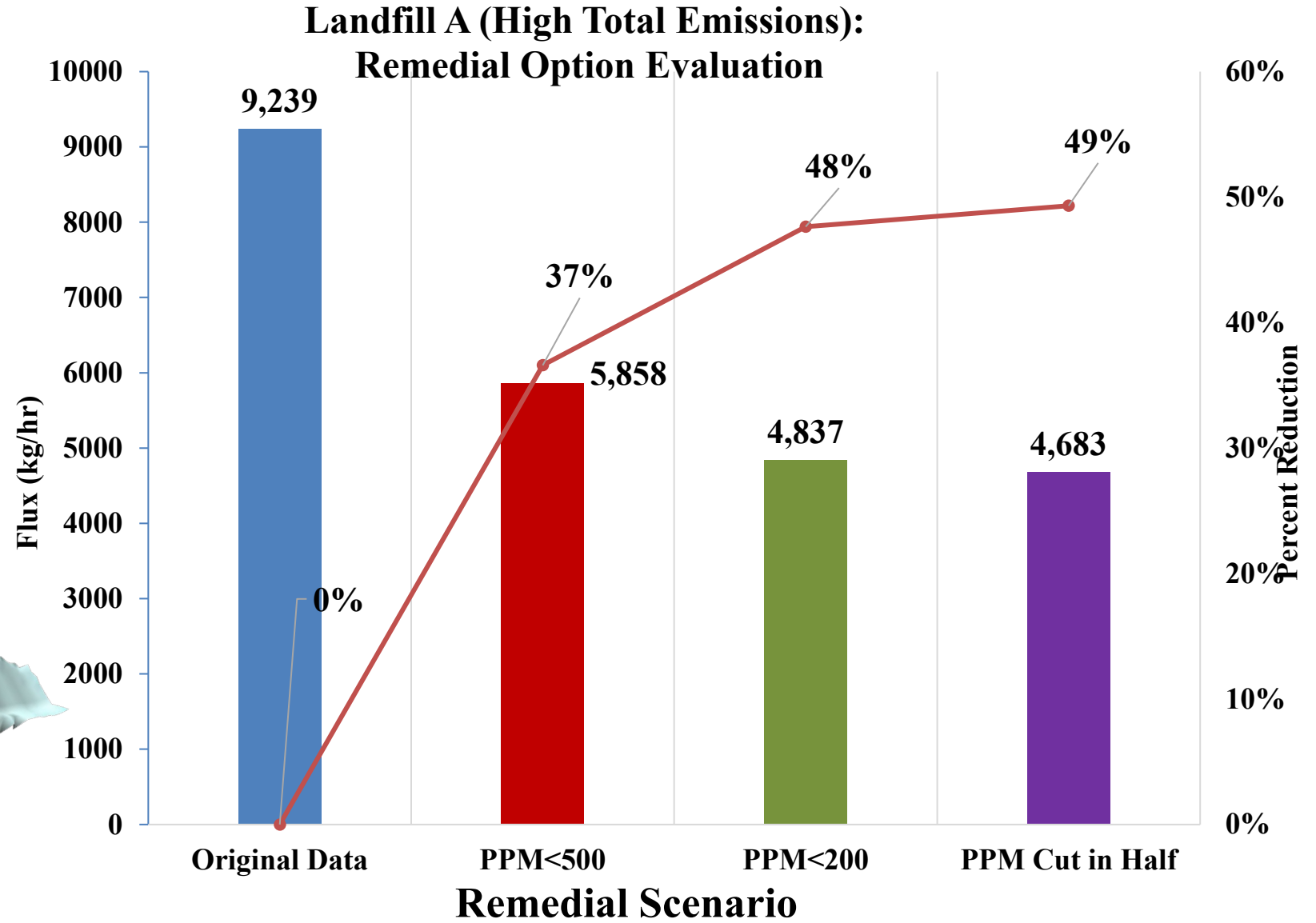
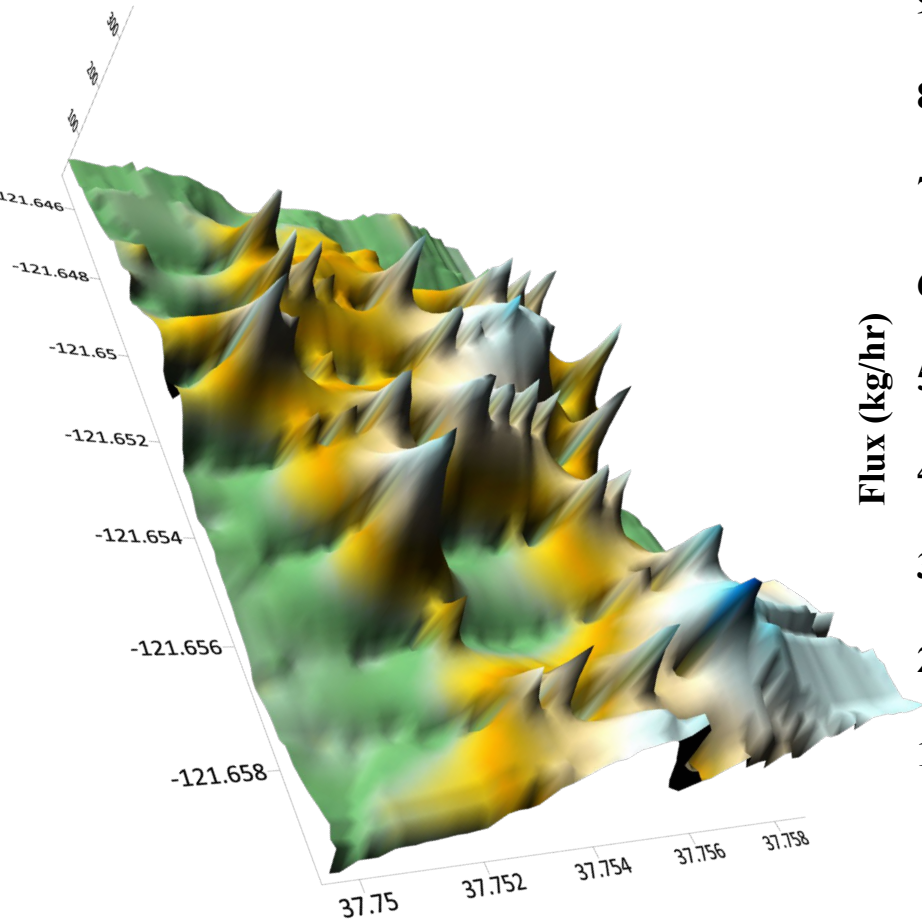
Contributions To Total Emissions



- Low flux contribution kg/hr
- Medium flux contribution kg/hr
- High flux contribution kg/hr

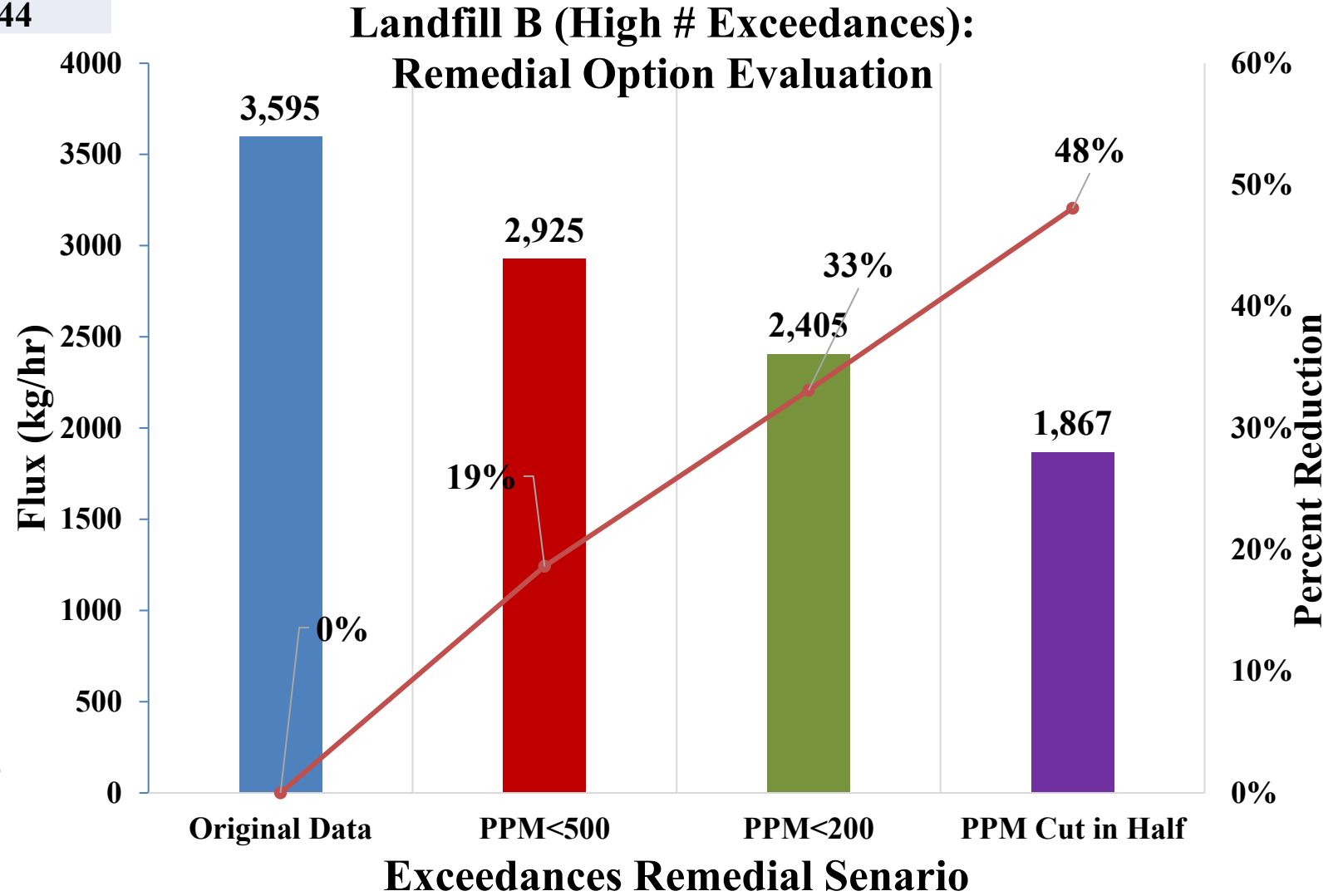
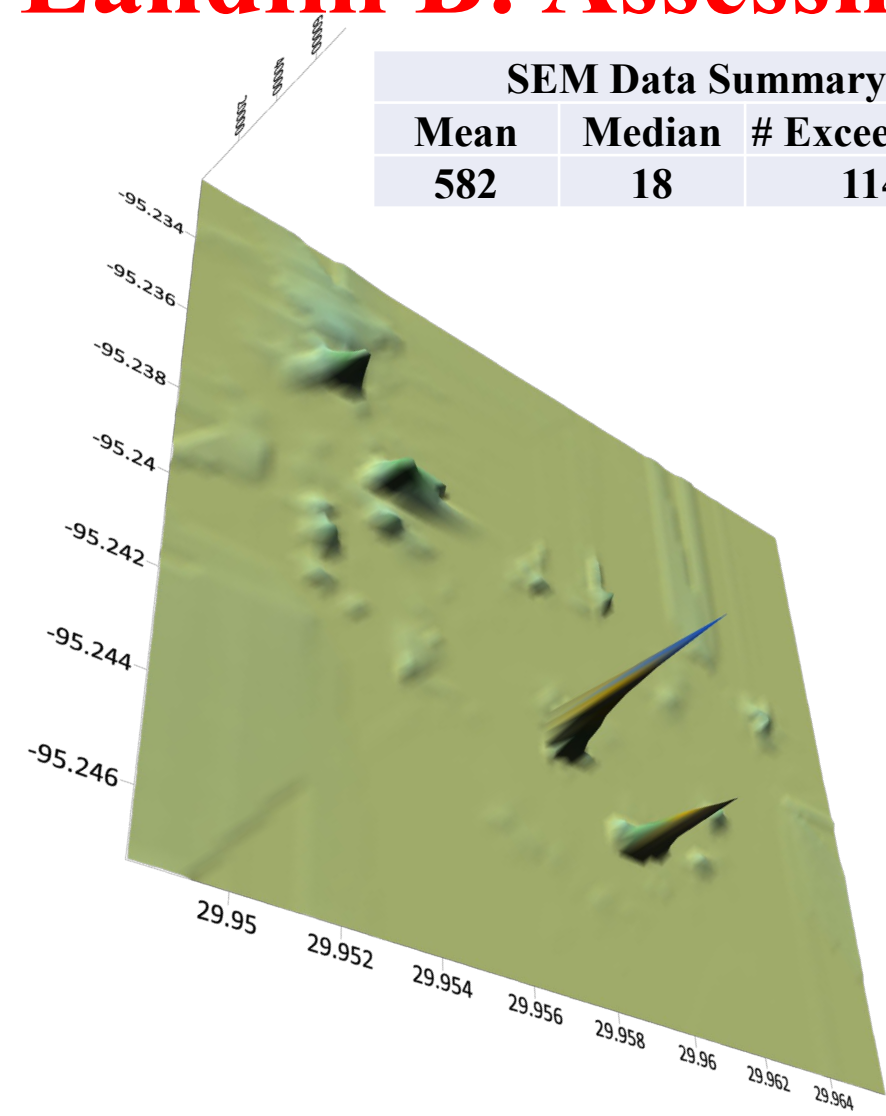
# Landfill A: Assessment of Possible Remedial Approach

SEM Data Summary		
Mean	Median	# Exceedances
1473	60	103



# Landfill B: Assessment of Possible Remedial Approach

SEM Data Summary		
Mean	Median	# Exceedances
582	18	1144



# Using a Digital Twin Approach for Designing and Evaluating Landfill Gas Emissions Modeling and Monitoring

## Assessing the Uncertainties in Integrated Mass Enhancement (IME) in Landfill Methane Emissions Applications

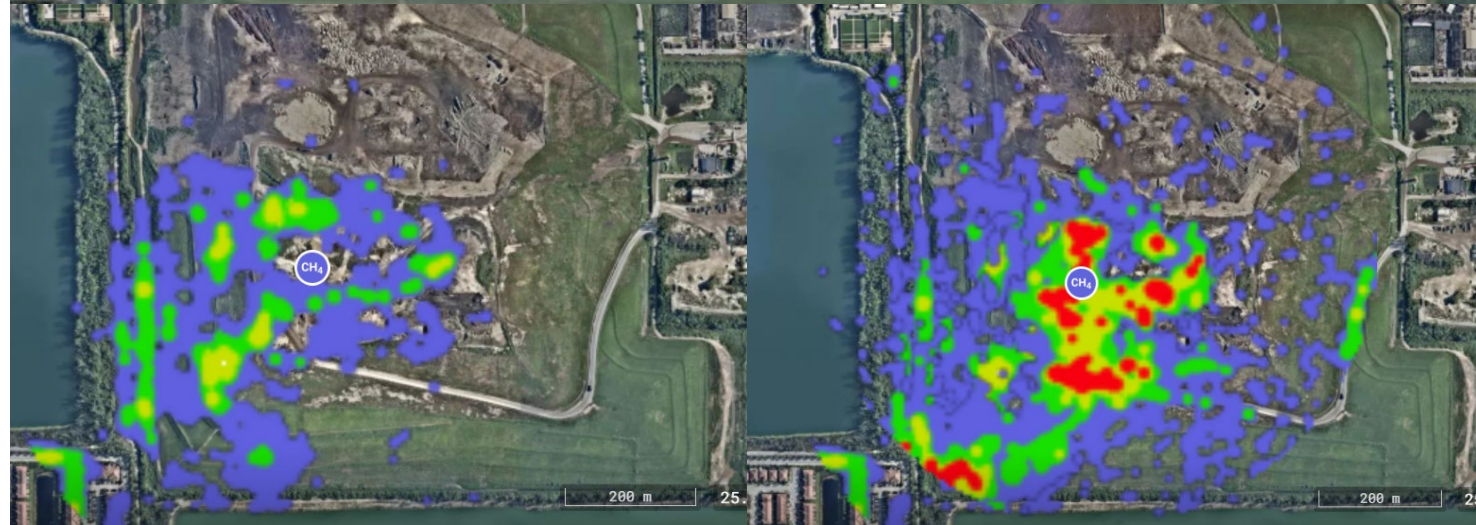


FAMU-FSU  
College of Engineering



UCF | College of Engineering  
and Computer Science

UNIVERSITY OF CENTRAL FLORIDA



# Landfill Digital Twin: Virtual Controlled Release Experimental Site

Create a prototype digital twin of a selected Florida landfill and Demonstrate its utilities in designing and evaluating landfill methane emissions modeling and monitoring approaches

Digital twin is the digital “clone” of a real-world system

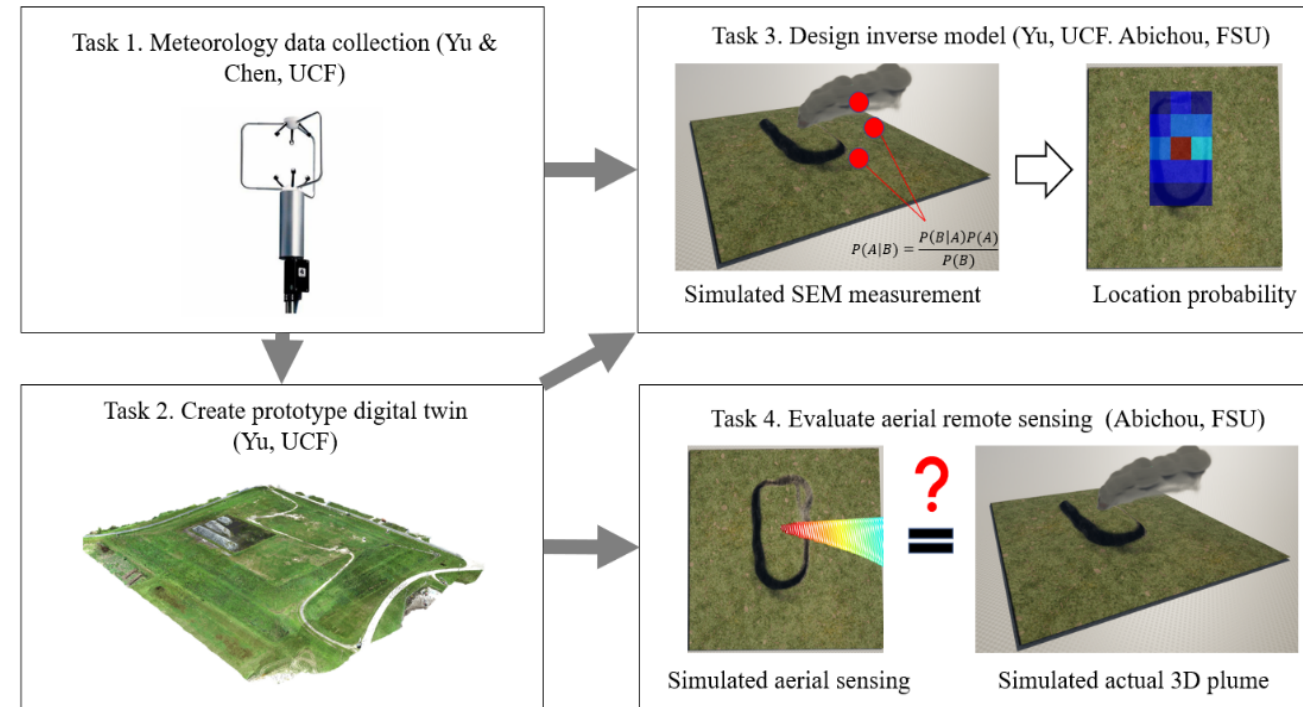
- Virtually represent real-time operating status
- Simulate physical, operational, and environmental characteristics

Digital twin enables **repeated experiments** not feasible in real world, such as iteratively designing, developing, and validating methane monitoring and modeling approaches

Digital twin can also be used to **simulate other aspects of landfill** such as scenario planning and operation forecasting

**Real-world sensor data** can also be integrated

Goal: Demo utility of landfill digital twin in methane emissions modeling and monitoring

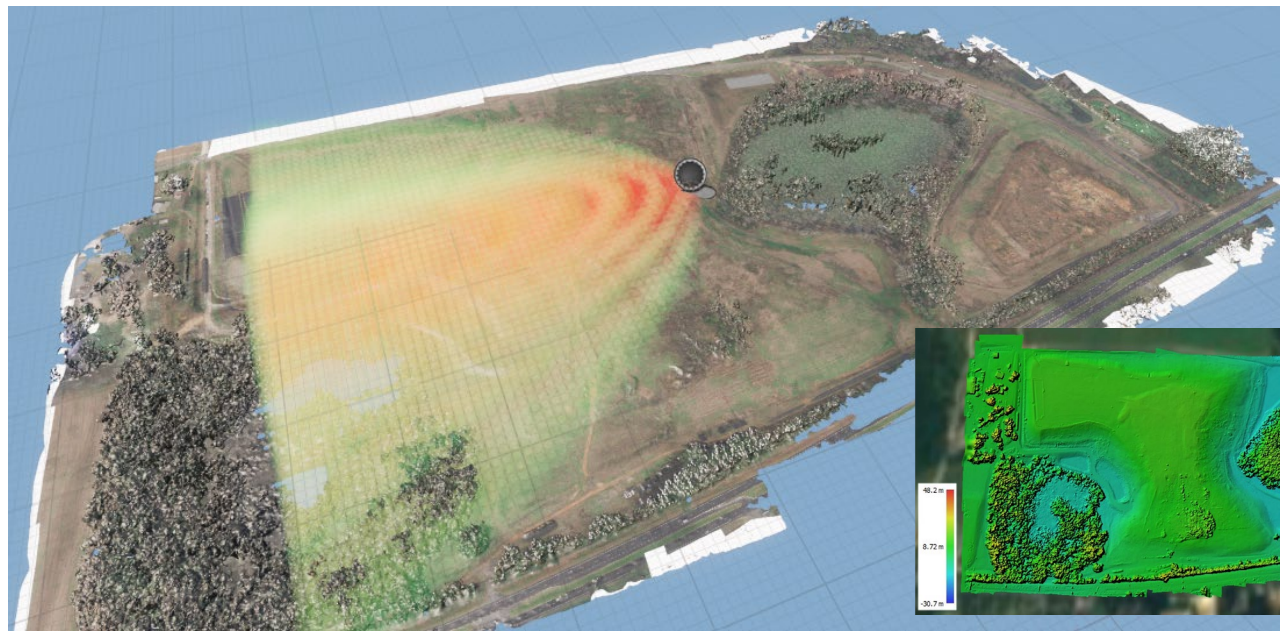
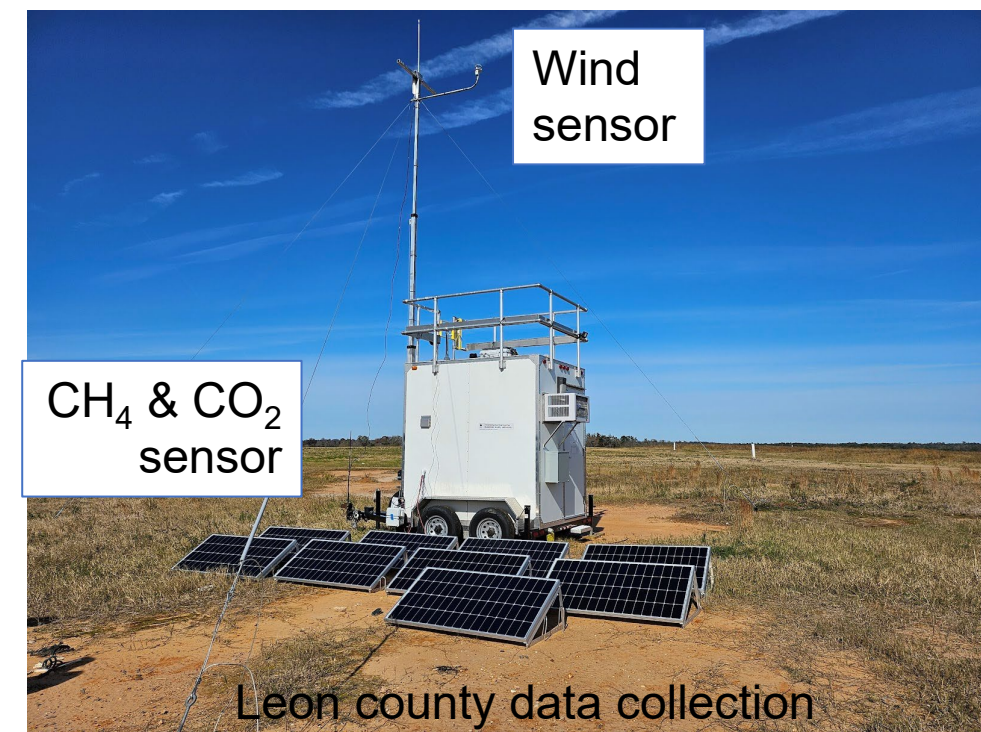


Design and/or evaluate CH<sub>4</sub> monitoring/modeling methods (SEM, Continuous Monitoring, Drones, Downwind, Aerial, ... techniques)

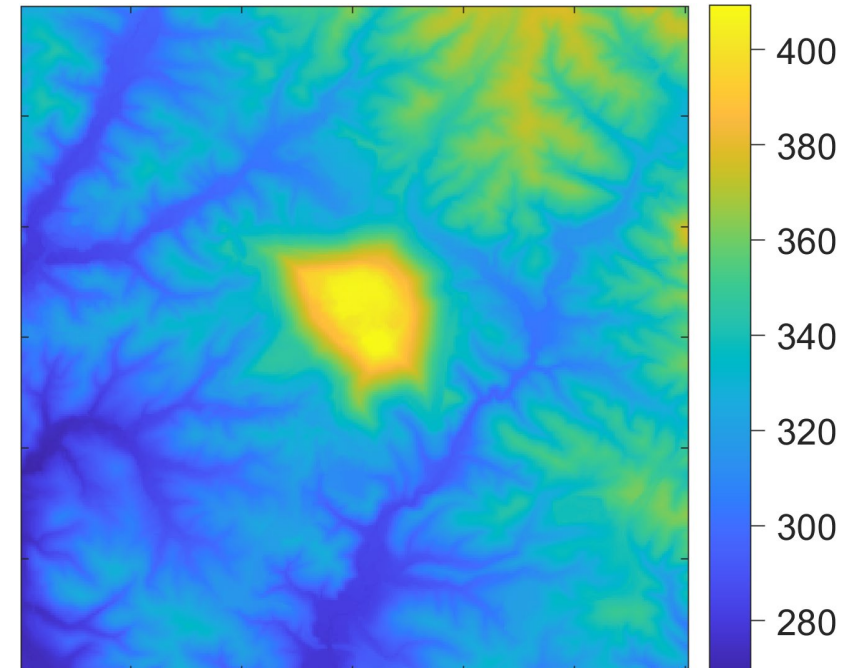
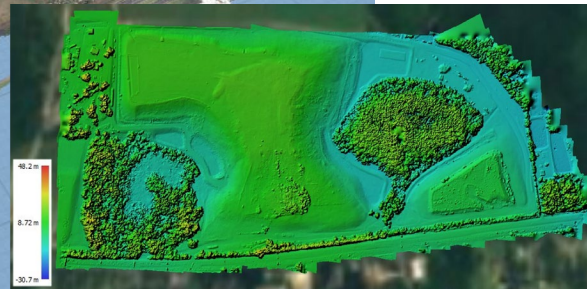


# Created Prototype Digital Twins

- Goal: Generating high resolution 3D CH<sub>4</sub> data & visualization in space and time
  - Collected high resolution terrain data for Leon County landfill
  - Obtained high resolution terrain data from a Georgia landfill
  - Created landfill digital representation in Unreal Engine
  - Simulated 3D CH<sub>4</sub> field using AERMOD model
- Collected wind data at 10 m for 3-4 months

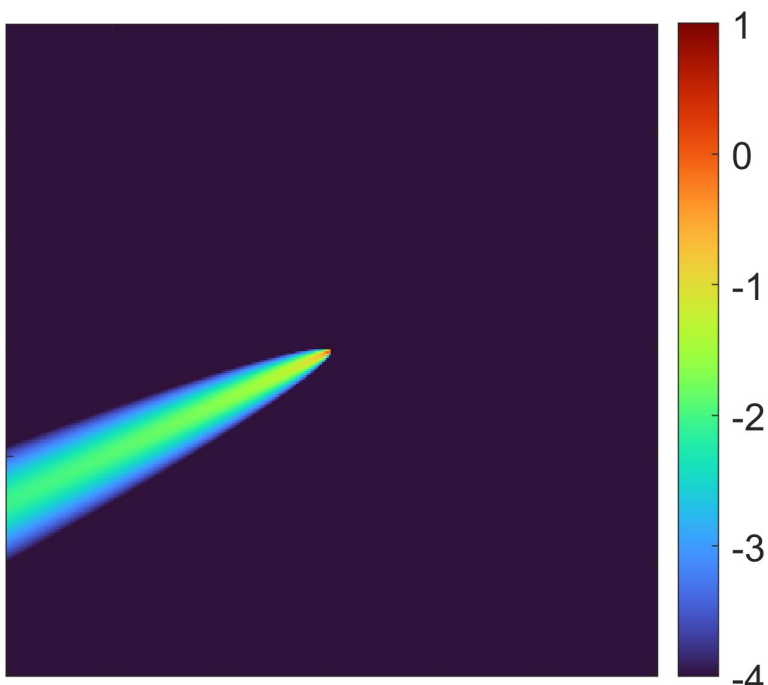
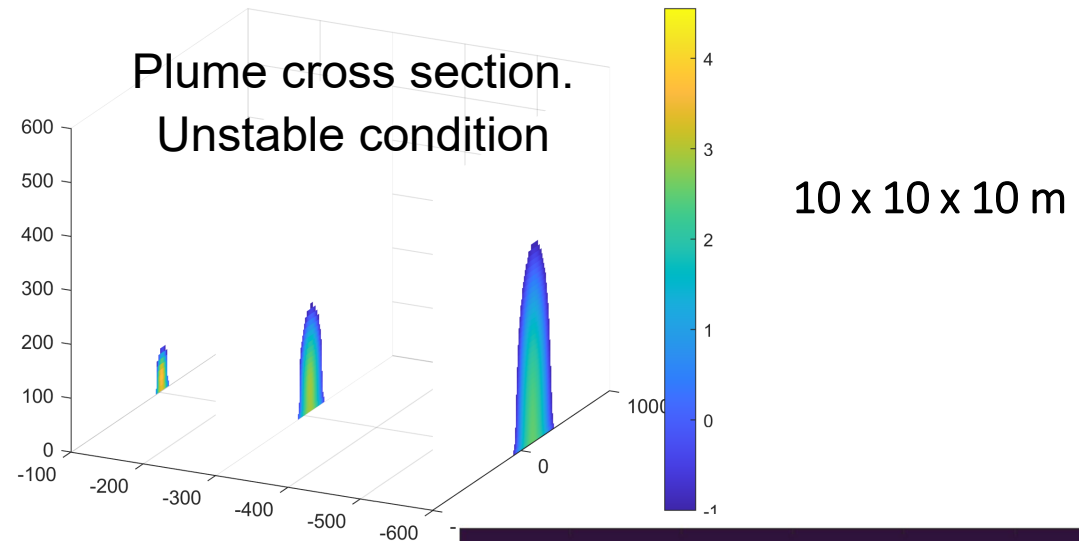
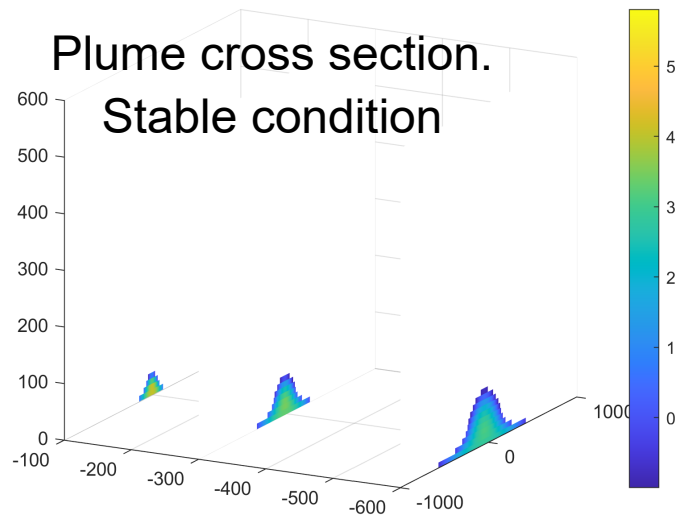


Flat and Complex Terrain



# AERMOD Modeling and Column Concentration Integration

- Performed many AERMOD for 2168 hours, about 90 days: **Generated 2168 scenes**



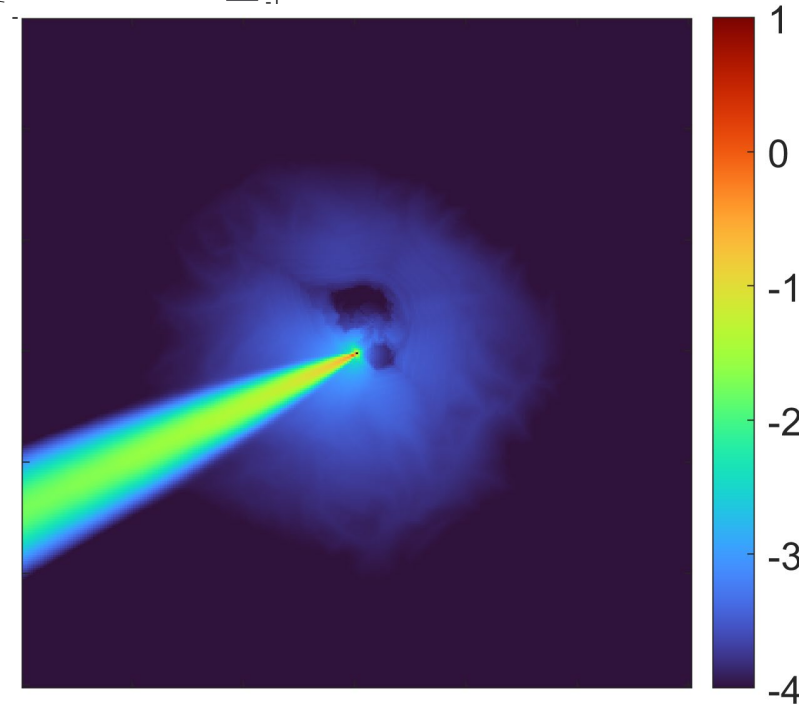
## Vertically integrated (0-1500 m)

AERMOD Results,  
No Background.  
log<sub>10</sub> (kg per pixel).  
True rate is 100 kg/h

**2168 Hourly scenes**

Flat terrain

Complex terrain



ppm.m



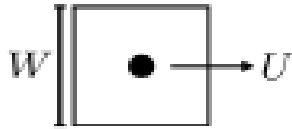
Flux: Mass/Time

Gaussian Plume



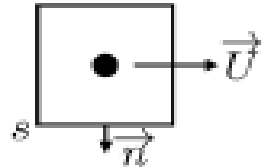
$$Q = U \Delta\Omega(x, y) \left( \sqrt{2\pi} \sigma_y(x) e^{-\frac{y^2}{2\sigma_y(x)^2}} \right)$$

Local mass balance



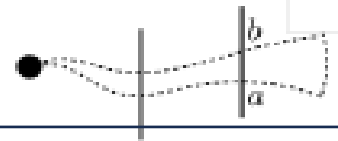
$$Q = UW \Delta\Omega$$

Gauss theorem



$$Q = \oint_s \Omega(s) \vec{U} \cdot \vec{n} ds$$

Cross-sectional flux (CSF)



$$Q = U \int_a^b \Delta\Omega(x, y) dy$$

Integrated mass enhancement (IME)



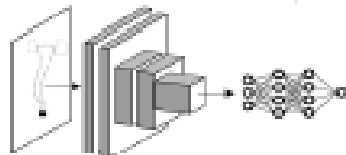
$$Q = \frac{U_{\text{eff}} \text{IME}}{L}$$

Angular width



$$Q = f(\text{IME}, \theta)$$

Machine learning



$$Q = \text{CNN}(\text{Plume image})$$

IME approach Varon et al. (2018) and others

# Sources of Uncertainties in IME Emissions Rate

Flux: Mass/Time (kg/h)

$$U_{\text{eff}} = 1.1 \log U_{10} + 0.6$$

Uncertainties in  $U_{\text{eff}}$

$$Q = \frac{U_{\text{eff}}}{L} \text{ IME}$$

Uncertainties in L:  
Length of plume m

Uncertainties  
in IME  
(kg of methane)

HRRR (~3 km resolution)  
GEOS-FP (~25 km resolution)  
On Site wind data

Our analysis focused on:

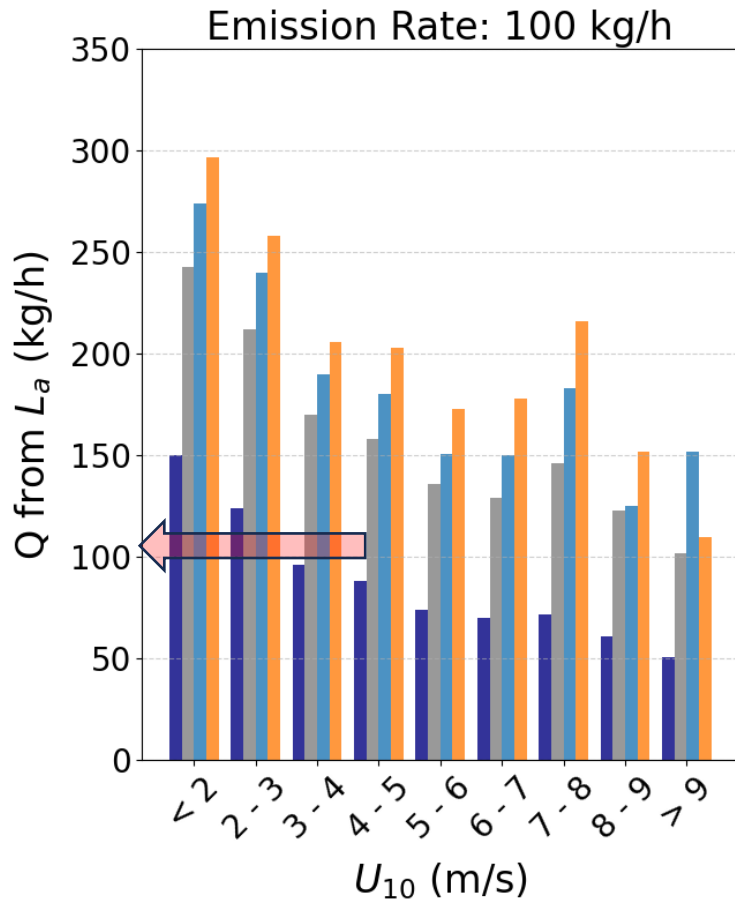
- Wind speed
- Noise levels
- Terrain topography
- Sources of  $U_{10}$  wind data.

Author	$U_{\text{eff}}$
(Cusworth et al., 2020)	$1.1 \log U_{10} + 0.6$
(Roger et al., 2024)	$0.34 U_{10} + 0.44$
(He et al., 2024)	$0.37 U_{10} + 0.64$
(Ayasse et al., 2019)	$U_{10}$
(Varon et al., 2019)	$\log U_{10} + 0.5$
(Guanter et al., 2021)	$0.34 U_{10} + 0.44$
(Ayasse et al., 2023)	$1.1 \log U_{10} + 0.6$
(Sánchez-García et al., 2021)	$0.12 U_{10} + 0.38$
(Thorpe et al., 2023)	$U_{10}$
(Irakulis-Loitxate et al., 2021)	$0.34 U_{10} + 0.44$
(Maasakkers et al., 2022)	$0.34 U_{10} + 0.66$ for $0.34 U_{10} + 0.42$
(Foote et al., 2021)	$U_{10}$
(Chulakadabba et al., 2023)	$\log U_{10} + 0.6$
(Pei et al., 2023)	$0.34 U_{10} + 0.44$
(Varon et al., 2020)	$1.14 U_{10}, 1.24 U_{10}, 1.16 U_{10}$
(Ehret et al., 2022)	$0.9 \log U_{10} + 0.6$
(Gorroño et al., 2023)	$0.23 U_{10} + 0.74$
(Marjani et al., 2024)	$0.34 U_{10} + 0.44$
(Schuit et al., 2023)	$0.59 U_{10}$
(Bruno et al., 2024)	$0.23 U_{10} + 0.7$
(Pang et al., 2023)	$0.55 \log U_{10} + 0.62$

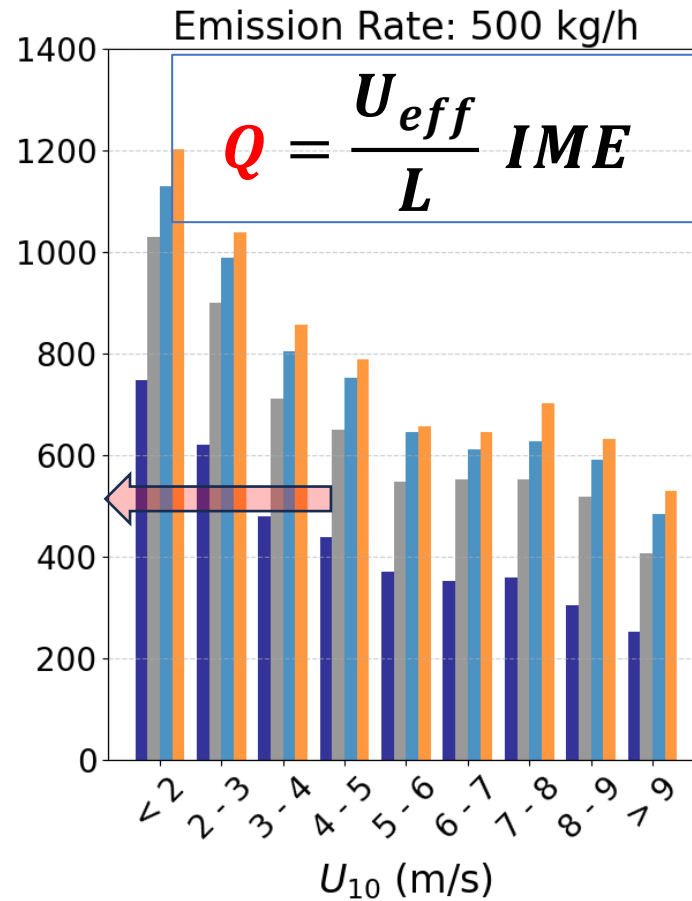
# Emission Rate Q, using the IME Method

## Flat Terrain

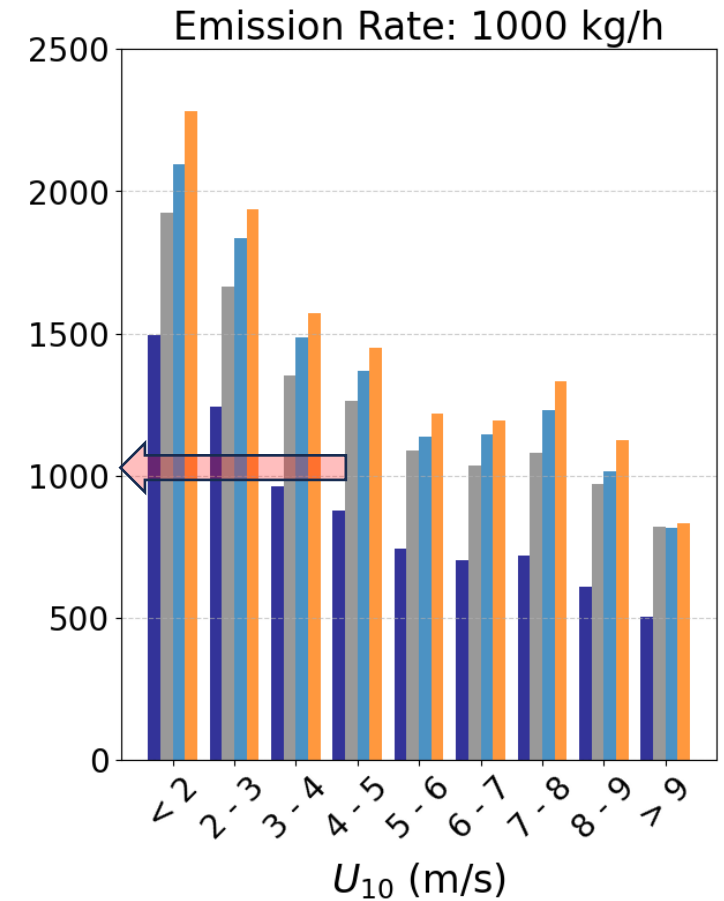
**1. Over Estimation at low wind speed. Worse with noise**



**2. Under Estimation at high wind speed. Worse with no noise**



**3. Noise leads to higher rates at all wind speeds**



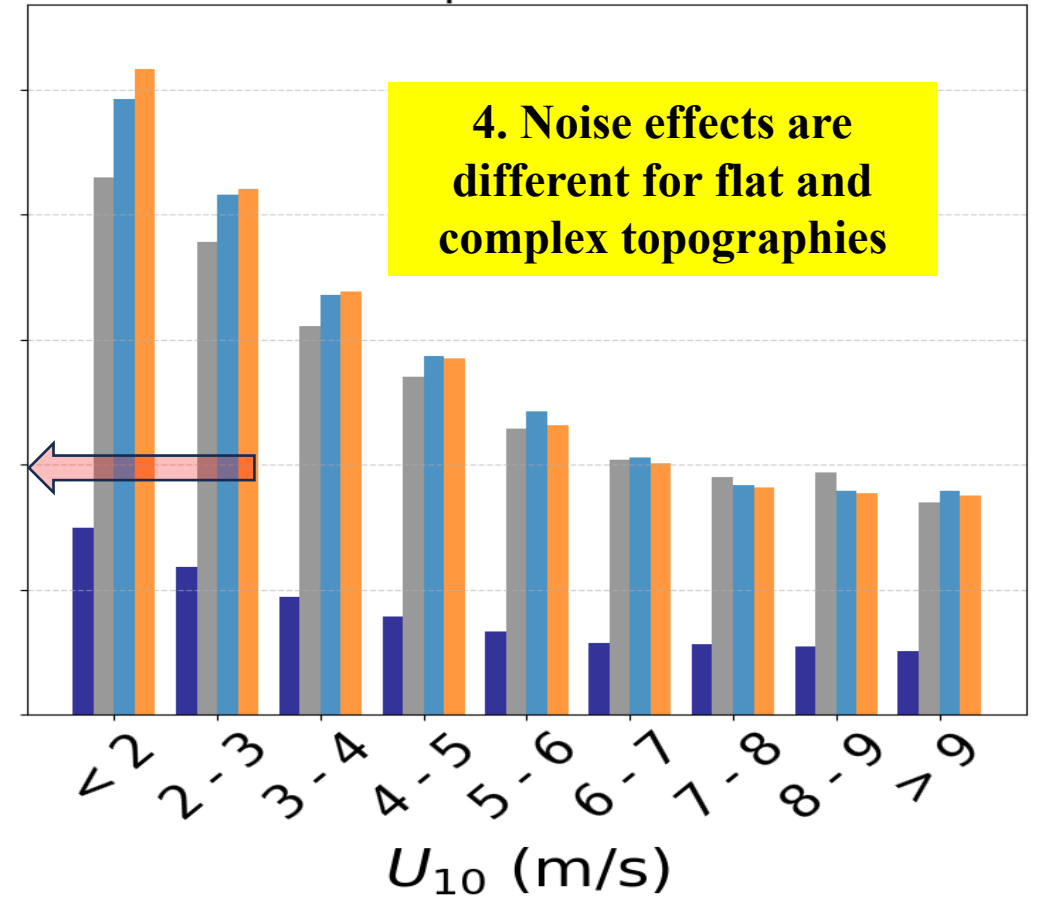
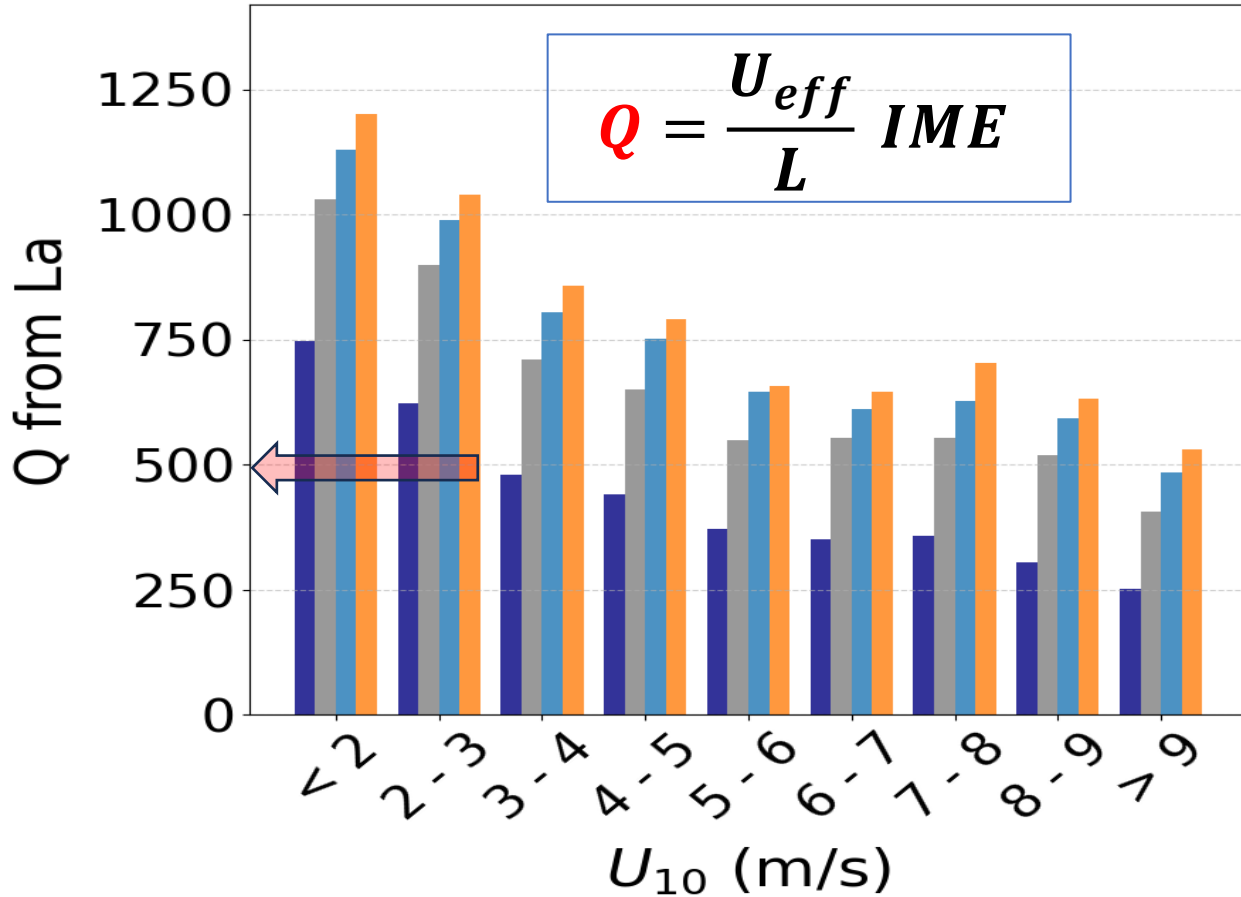
0% Noise    1% Noise    3% Noise    5% Noise

# Emission Rate Q, using the IME Method

## 500 kg/h Emission Rate across Flat and Complex Terrain

Estimated Q from La for 500 kg/h Emission Rate  
(Flat Terrain)

Estimated Q from La for 500 kg/h Emission Rate  
(Complex Terrain)



0% Noise    
  1% Noise    
  3% Noise    
  5% Noise

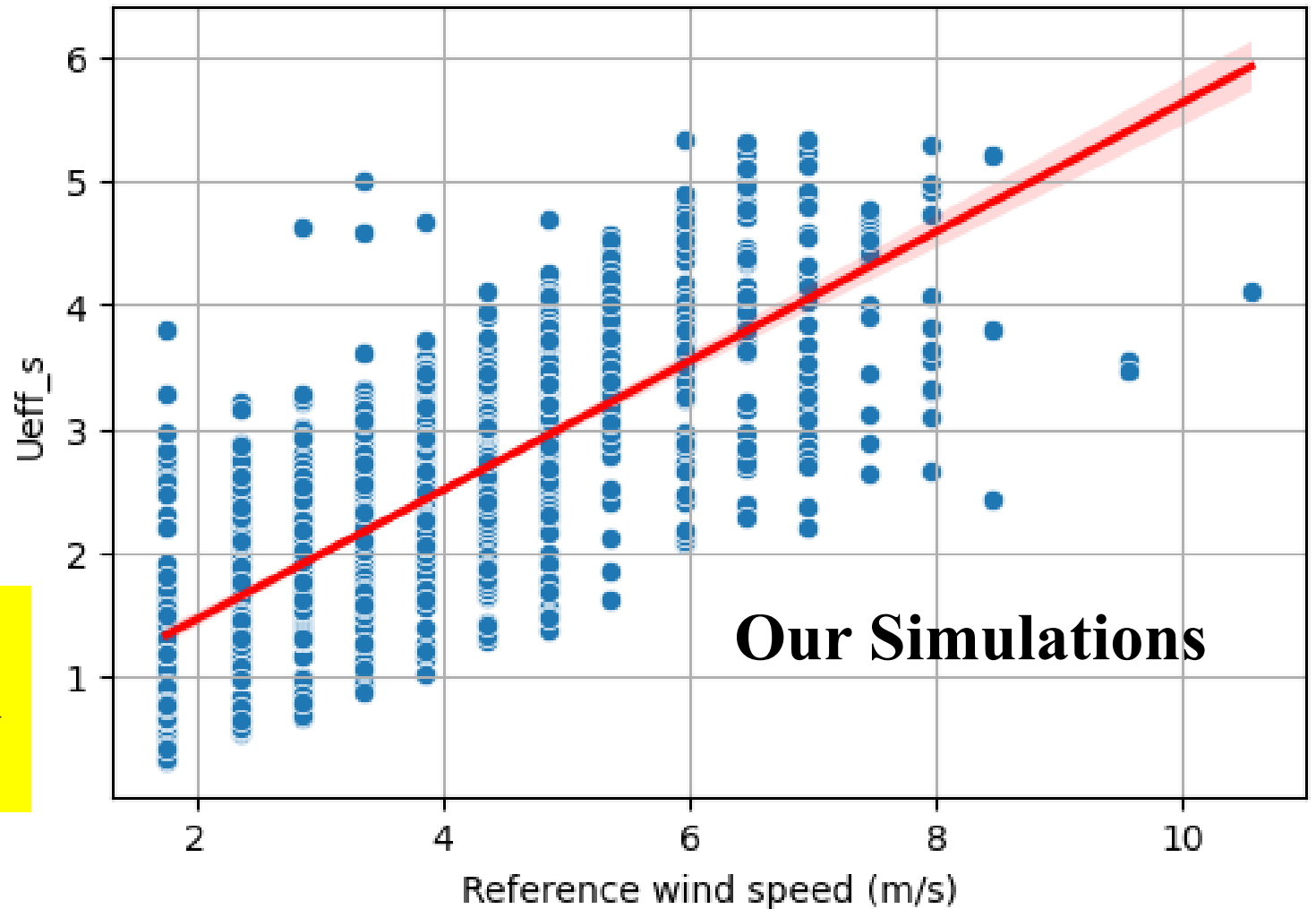
# Sources of Uncertainties

**Varon's Simulation:**  
**Reference Wind Speed:**  
Controls simulations

$$U_{\text{eff}} = 1.1 \log U_{10} + 0.6$$

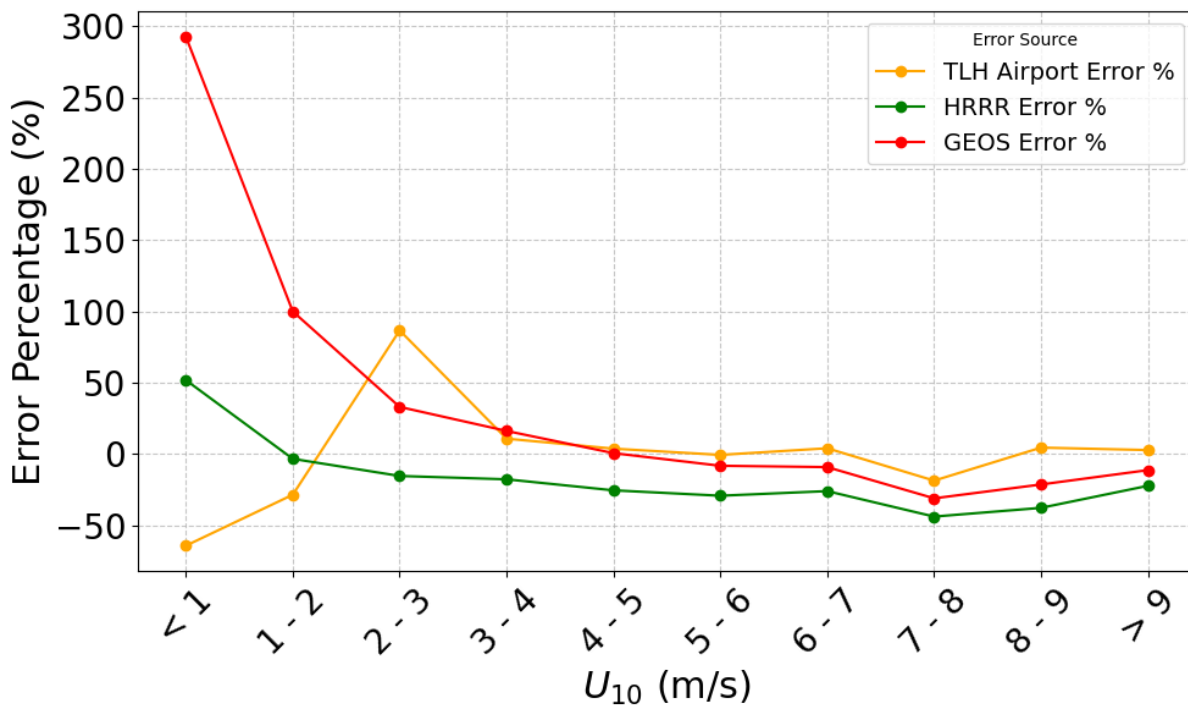
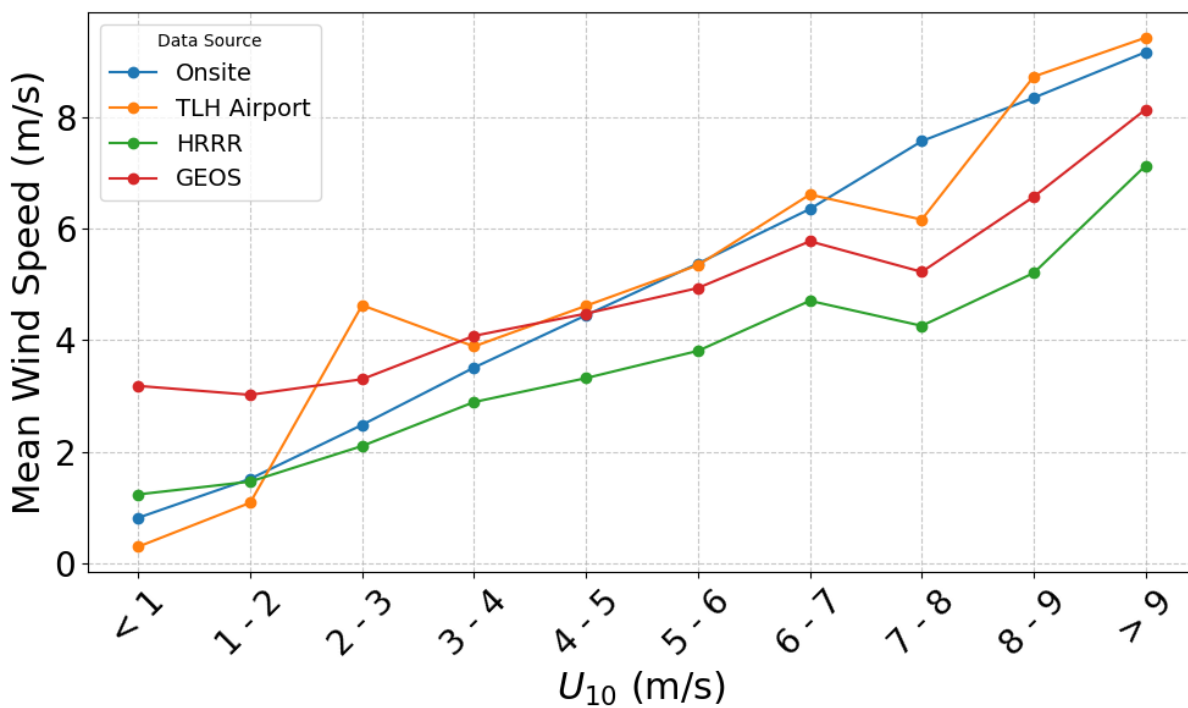
**$U_{\text{eff}}$  is affected by other  
parameters besides wind speed  
Need to more research!!!!!!**

Scatter Plot:  $U_{\text{eff\_s}}$  vs Reference wind speed (m/s) (Daytime Hours)



# Other Sources of Uncertainties

**Cross-comparison of mean wind speeds from on-site measurements, nearby TLH airport, HRRR and GEOS models.**



$$U_{\text{eff}} = 1.1 \log U_{10} + 0.6$$

**Large difference between on site and database global wind data models especially at low wind speed**



## Key Takeaway on IME Approach

- Current IME algorithm may have significant uncertainties
  - $U_{eff}$  wind formula may not account for all atmospheric conditions and the disproportionate change of mass enhancement and plume scale
  - Terrain feature could impact IME accuracy
  - The use of wind data from weather model may introduce more uncertainties
  - $\sim 10$  x over-estimation possible
- Location specific calibration w/ local wind data may be necessary

- ✓ **We need to develop site-specific or conditions-specific  $U_{eff}$  Equations each satellite observation?**
  - ✓ **We need more controlled releases under diverse atmospheric condition for IME calibration ?**

# Deliverables



Delangel Jorge M.  
**Student**  
(Graduated 2023)



Sakina Amankwah  
**Student**  
**Graduated (12/2024)**  
Looking for a Job!!!

# Questions?

**Tarek Abichou**

Professor

Civil & Environmental Engineering  
FAMU-FSU College of Engineering

Phone: (850)410-6661

E-mail: [abichou@eng.famu.fsu.edu](mailto:abichou@eng.famu.fsu.edu)

## Contact Information

